

INTEGRATING AN ANIMATION RIG INTO A CREATURE PIPELINE

AWGUA Maya Master Class August 2001

Integrating an animation rig into a creature pipeline: Presentation Outline

Presenter: Jason Schleifer
Weta Digital, Wellington, NZ

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These data files are included with the coueware data:

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- jsCreateCreature.mel
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- jsGetShape.mel
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Scenes

- backSolver_start.mb*
- boneStructure_done.mb*
- boneStructure_start.mb*
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- lrKeithAnim.mb*
- lrKeithGimbal_done.mb*
- lrKeithGimbal_start.mb*
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- rings.mb*

Other

- web pages and sample movies
- backSolver_end.mb
- boneStructure_start.mb
- boneStructure_done.mb

I. Developing the Pipeline

What is a pipeline?

A pipeline is the basic path that a shot, or a portion of a shot can take from start to finish.

Example 1: Film I/O Pipeline:

- Scan film into computer using film scanner.
- Convert images to all resolutions/formats for production (TV res for animation, 1k and 2k for comp).
- Put images in logical location.
- Notify appropriate parties.

Example 2: Modeling Pipeline:

- Take physical sculpture and trace contour lines around model
- Digitize contours into computer.
- Build rough surface based on mesh.
- Refine, and deliver final subdivision or nurbs surfaces.

Example 3: Shot pipeline.

- Bring scanned plates online
- Matchmove a camera to the plates
- Build relevant 3D data (floor plane, interaction geometry).
- Animate creatures to the scene
- Add FX
- Render separate elements
- Composite all elements together.
- Write final frames to film.

Obviously building a facility which runs well requires smaller pipelines which fit into the broader structure of creating a shot. In this course, we're going to focus on the character animation, or creature rig aspect of the pipeline:

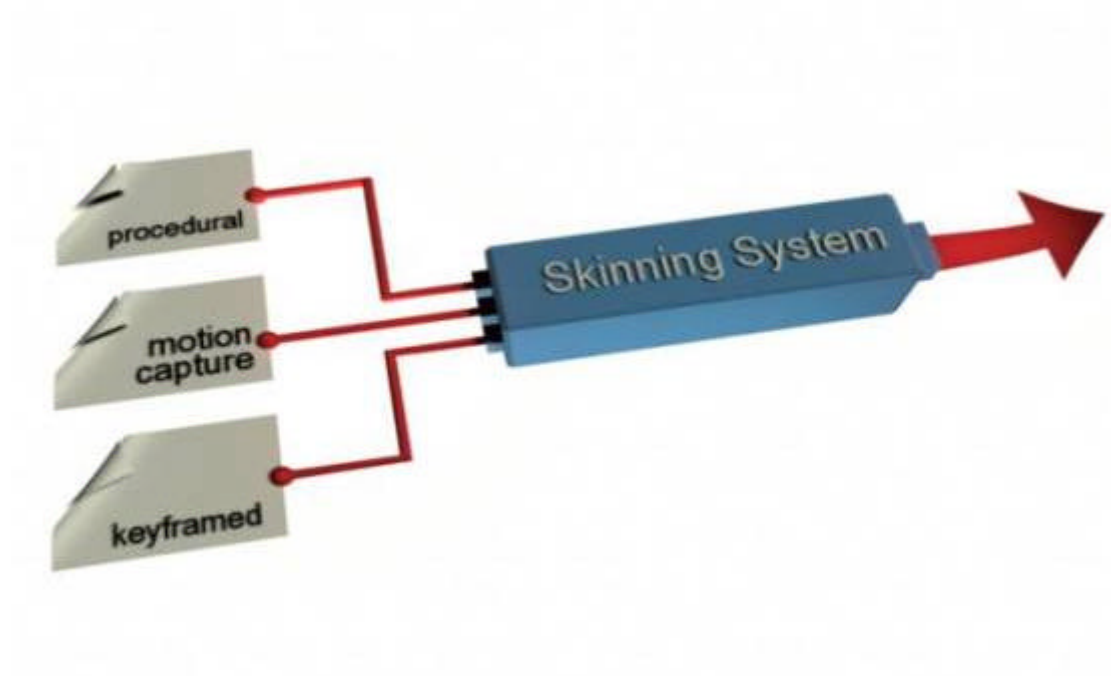
- Building a skeletal structure that makes sense.
- Developing controls for that skeletal structure.
- Delivering the motion to the skinning system in a consistent way.

Where Does the Animation Rig fit in the Pipeline?

In order to determine how we're going to build our puppets to fit into the production pipeline, it's important to know what part of the pipe they are, and what their relationship is with other aspects of the pipe. To do this, you need to determine the following things:

- What type of motion are you going to be dealing with? Hand keyed animation? Motion capture? Procedural? A combination of those?
- What packages are involved in the process? Are they all Maya based, or do you have to integrate with Houdini, Softimage, Mirai, etc.

Basically you want to ask yourself, How am I going to get this motion to that skinned creature?.



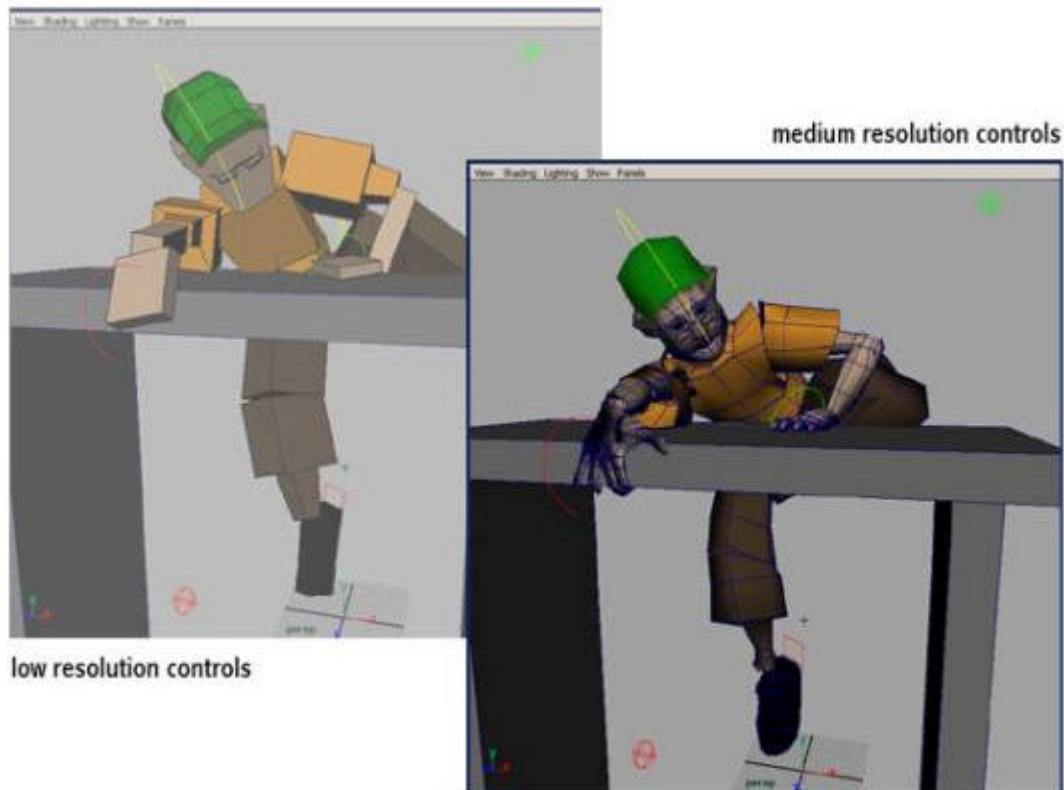
The image above shows a simplified flow of motion through the skinning system at Weta Digital. We had at least three different types of motion being delivered through the system: procedurally generated, motion capture, and keyframe animated.

In order to keep things consistent and easy to keep track of, we knew that we would need one method of transferring animation from the motion capture, the rigs, and the procedural system to our skinning system.

There are basically two methods for transferring animation from a creature rig to a skinned creature:

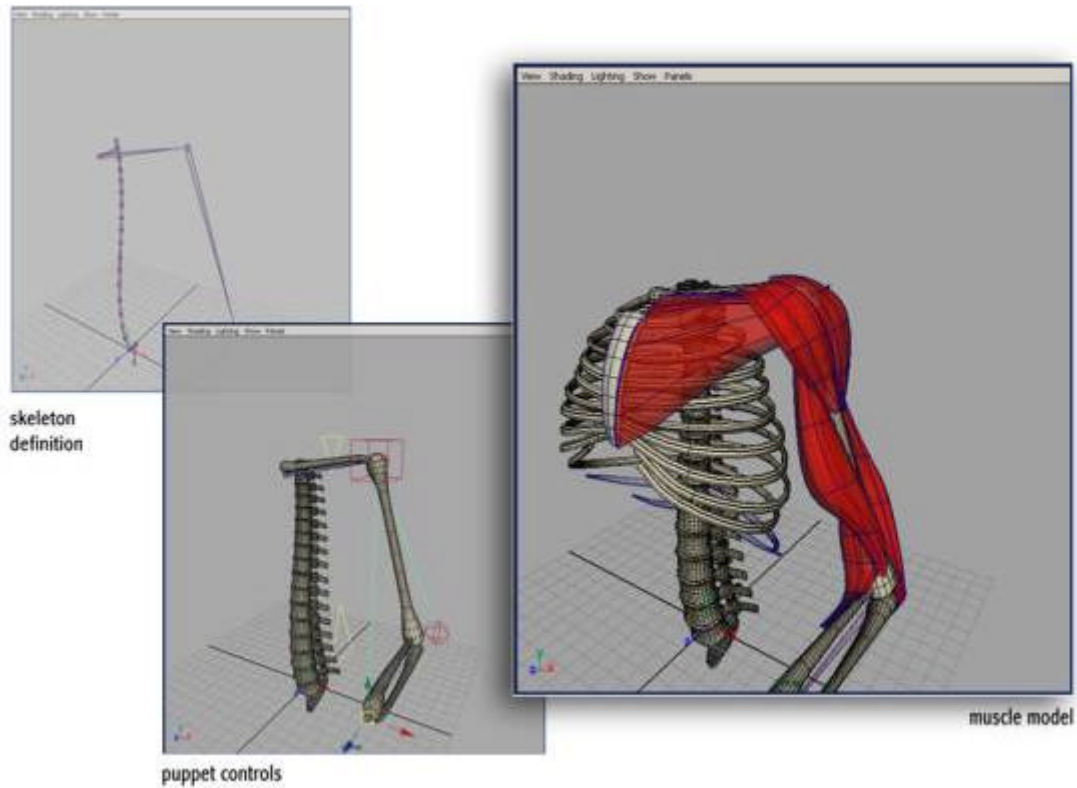
- Control based
- Skeletal based

Control Based Animation Transfer



- Animation gets copied from the animator controls, and applied to those same controls on a more complicated skeleton.
- This setup usually involves a few resolutions of a creature:
 - **Low resolution**, easy and fast to animate.. usually a body control, arm and leg controls, and a head control.
 - **Medium resolution**, still somewhat quick to animate, but has more detail.. fingers, toes, eyes, facial, etc. Basically everything you need about 90% of the time
 - **High resolution**. This has everything on the creature you could possibly animate maybe even all the skinning is applied. This is a slow creature to move, but you can control every aspect of it.

Skeletal Based Animation Transfer



- Animation gets copied from the bones themselves, to a creature rig which is driven by the same bone structure.
- Any control can be applied to the skeleton, as long as the enveloping and puppet models have the same controls the animation will come across.

Which to use?

- Both methods work fine, and have been used successfully in many productions. Which method you choose depends on what the pipeline is you need to use.
- A benefit to the control based animation transfer is that the animator can tweak the final skin of their creature with the same controls they use to animate with. They can at any point make those fine adjustments, always knowing exactly what they're going to get.
- With the skeletal based animation system, once the skeleton is defined the animator and TD can do whatever they want to the control structure, and the animation will always come across correctly. This is extremely important if you have a creature that needs different setups depending on the situation they're in. You only have to build ONE muscle model, but you can have 15 different control structures depending on what's needed. Conversely, you can have 47 different muscle models with fixes for certain angles (if necessary), and as long as the skeleton is the same you can take the animation across.

II. Defining the "Creature" (step by step)

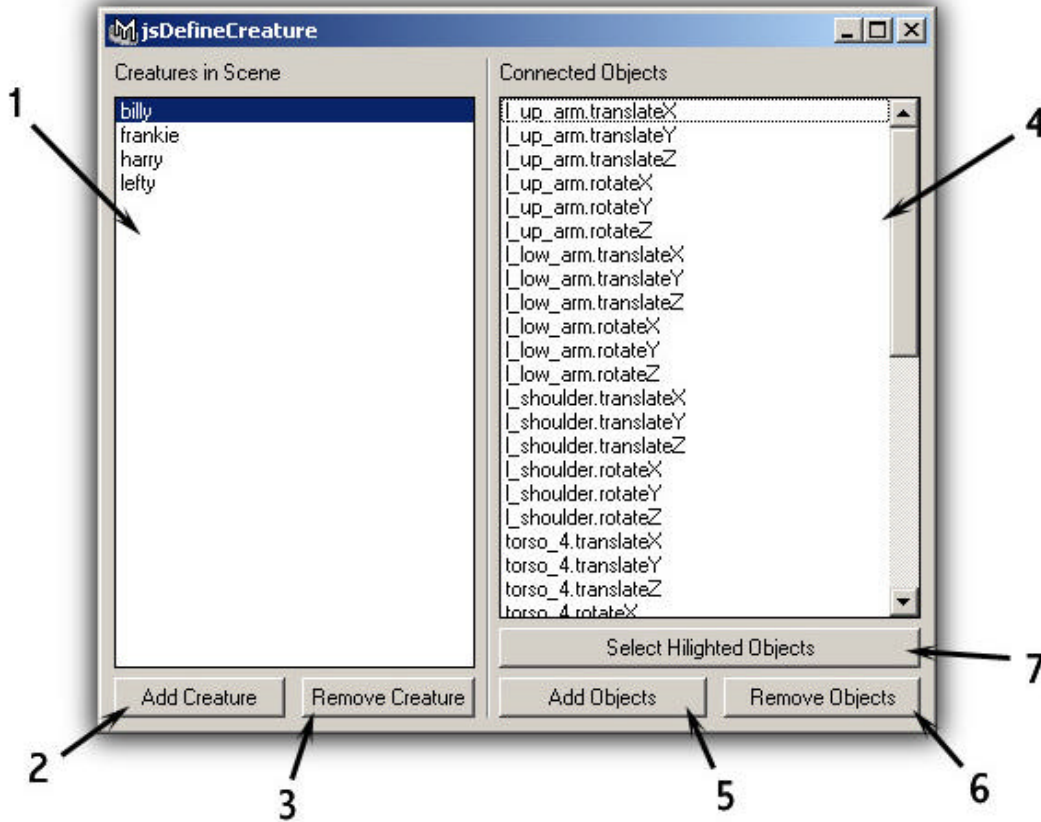
What is a creature?

- In order to be able to consistently work with your animation rig and muscle model, it's important to define what the "creature" is.
- The "creature" can be anything, really, as long as it's easily accessible and you can keep track of it. It's a handy place to keep notes about the setup, keep track of version numbers, even animation tips.
- At Weta we had a specific node which was our "creature" node. That was the parent of all the animation controls in the rig, and of the entire muscle model in the muscle setup. It allowed us to keep things neat and tidy when working with 50 characters in the scene.
- The creature node was also used to point to the ASF which was represented by that character. Because all our animation is being transferred using ASF/AMC, we need to know what ASF is being used (sometimes asf's would change for a creature).

jsDefineCreature.mel script

This script allows you to define which controls are going to be exported using **jsMovOut**, or imported using **jsMovIn**.

- Bring up the interface by typing "**jsDefineCreature**" in the script editor.



1. All the "creatures" in the scene.
2. Add a new creature to the scene.
3. Remove a creature from the scene.
4. All the connected objects for the selected creature.
5. Add selected objects to the current creature
6. Remove highlighted objects from the current creature
7. Select the highlighted objects.

Example:

- o Load IrKeithAnim.mb
- o Bring up jsDefineCreature.
- o Notice how there's a IrKeith creature in the scene.
- o Now we're going to add a "creature" for the platform.
- o Click **Add Creature** to create a new creature.
- o Call it "*platform*".
- o Highlight **platform**.
- o In the outliner, select *platform_twist*, *platform_tilt1*, *platform_tilt2*.
- o Click **Add Objects**.

Notice how the platform attributes are all shown in the UI. It will add all keyable attributes.

- o Select the attributes we don't want and remove them by clicking **Remove Objects**.

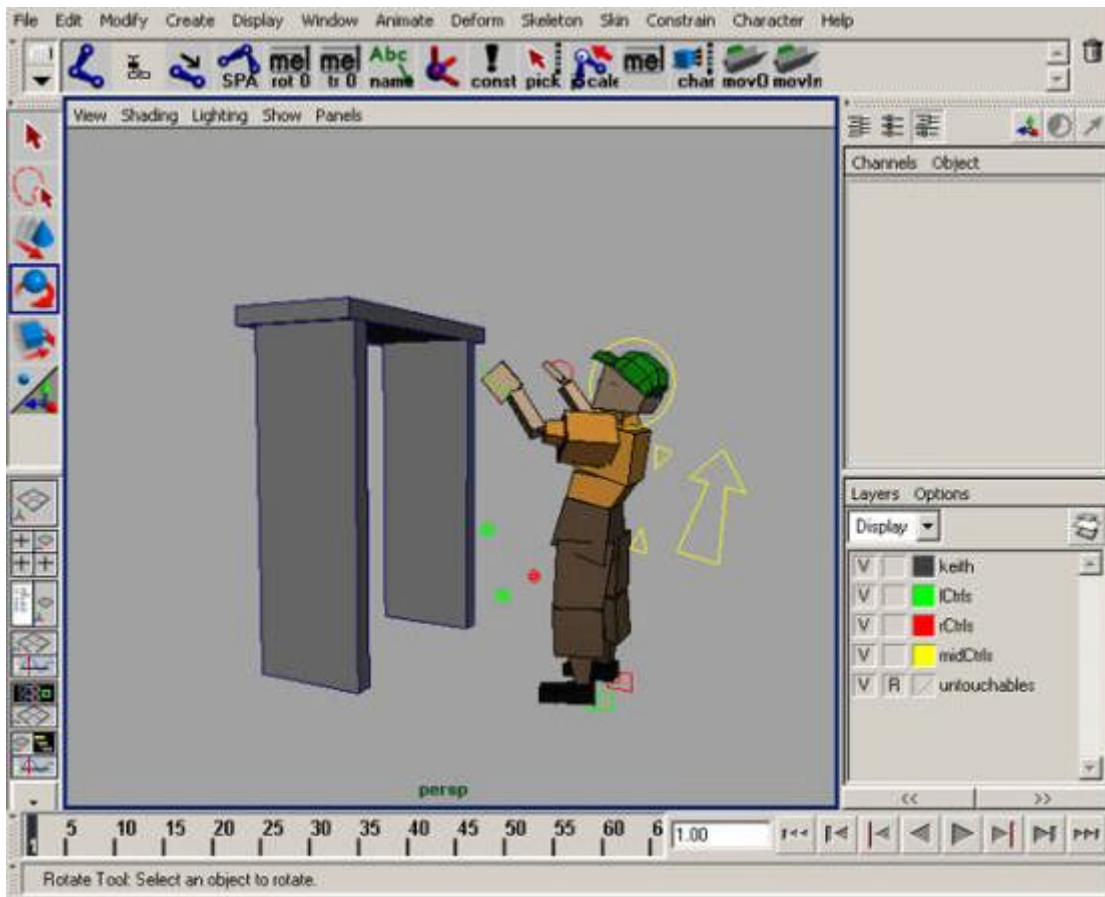
Now we have a platform creature!

jsMovOut.mel script

This script allows you to take the animation from a creature and write it out as mov data.

Use this script whenever you want to export frame-by-frame animation from a creature to a **mov** file.

Example:



- o Load **IrKeithAnim.mb**

This is blocking motion of **keith** attempting to jump onto a pillar of blocks. (view the *IrKeithJumping.avi*)

- o Bring up **jsMovOut**.
- o Select the IrKeith.

- Click **Export MOV**
- Enter the name of a **mov** file.

Maya will now export the information on those controls frame by frame.

jsMovIn.mel script

This script allows you to import the animation from a mov file onto a creature.

Use it when you've exported animation from a creature and you want to import it onto another creature.

Example:

- Open **mrKeithSkel.mb**

This is the medium resolution of the Keith puppet.

- Run **jsMovIn**.
- Pick **mrKeith**.
- Click **Import Mov**.
- Choose the **mov** file you generated from above.

This will now import the motion onto this medium resolution version of keith!

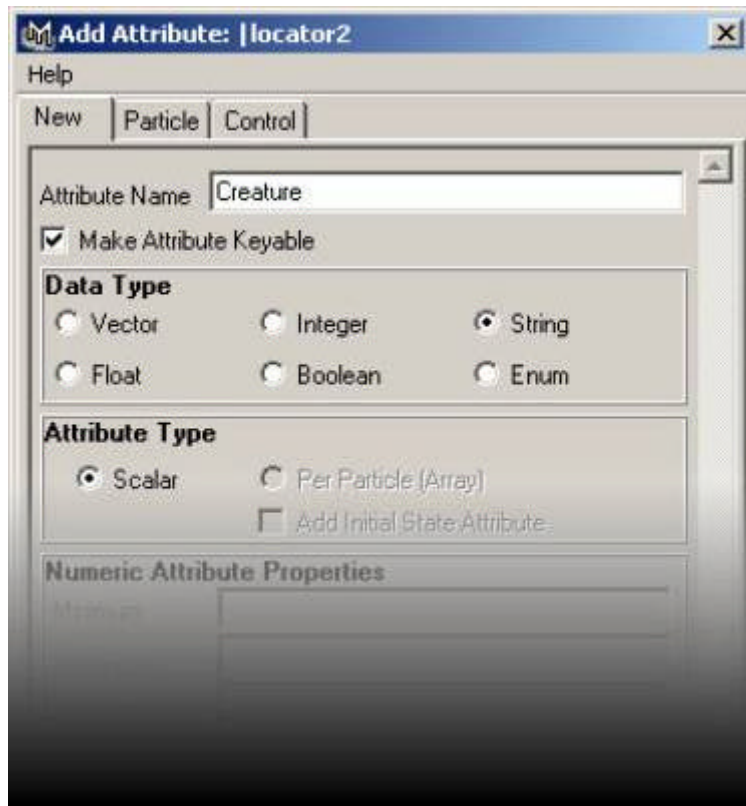
III. Defining a "type" of node (step by step)

Creating a "type" of node

The example of using **jsDefineCreature**, **jsMovIn**, and **jsMovOut** works because we've defined what the creature is, and we can search our scene for all the nodes of that type.

This is done by simply adding an attribute which we can search for.

- Create a locator, add an attribute called "**Creature**" of type string.
- Select **Create > Locator**
- Select **Modify > Add Attribute**;
- Name the attribute **Creature**, and make it type **String**;



Finding a creature

Now that we know that our "creatures" are actually locators with an attribute on them called "Creature", it becomes really easy to find. Using mel, we can type the following command:

```
ls -type spaceLocator;
```

This will return all the locators in the scene.

You can use the **attributeQuery** command to find out if an attribute exists on a certain node:

```
attributeQuery -exists -node <node> <attribute>;
```

Throw this whole thing into a loop, and you can easily find all the locators in the scene with the attribute of name **Creature**:

```
string $locators[0];  
string $creatures[0];  
int $c = 0;  
  
// get the list of locators  
$locators = `ls -type spaceLocator`;  
  
// cycle through each locator  
for ($loc in $locators)
```

```
{  
  
    // check and see if the attribute exists  
    if (^attributeQuery -exists -node $loc "Creature")  
    {  
  
        // if the attribute exists, add $loc to the list of creatures  
        $creatures[$c] = $loc;  
  
        // increment $c  
        $c++;  
  
    }  
  
}  
  
print $creatures;
```

If you want to get really tricky, you can throw the whole thing into a procedure called "findCreature", and add an option for a "type" of creature.

```
global proc string [ ] findCreature (string $type)  
{  
  
    string $locators[0];  
    string $creatures[0];  
    int $c = 0;  
  
    // get the list of locators  
    $locators = `ls -type spaceLocator`;  
  
    // cycle through each locator  
    for ($loc in $locators)  
    {  
  
        // check and see if the attribute exists  
        if (^attributeQuery -exists -node $loc "Creature")  
        {  
  
            // if the attribute exists, check and see if  
            // the creature is of the right type  
            $attrType = `getAttr ($loc + ".Creature")`;  
            if ($type == "")  
            {  
  
                $creatures[$c] = $loc;  
  
                // increment $c  
                $c++;  
  
            }  
  
        }  
  
    }  
  
}
```

```
        else if ($type == $attrType)
        {
                $creatures[$c] = $loc;

                // increment $c
                $c++;
        }
}

return $creatures;
}
```

Finding nodes which relate to the creature

Quite frequently, you'll need to execute scripts based on certain nodes of a creature. For example, at Weta, we had scripts to automatically switch between fk and ik using a single (or a few) button clicks. To do that, we had to know which controls were being used for fk, which for ik, and what attribute was dealing with the constraints. In the case of **jsMovIn** and **jsMovOut**, we need to know which nodes and attributes we're going to be exporting.

This can be done using names, but 99.9% of the time, the name you determine for a node is going to be changed, either through importing, or another object being named something similar.

Using connections to derive names from your scripts is really the only way to insure that you're not going have your scripts break each time they're executed.

To do this, add an attribute which is easily found by you, and is of type message. It can be multi, or not. It depends on what you're using it for.

You are going to Add the attribute, make the connection, and use listConnections to determine what the names are.

- **Adding the attribute:**

```
// add a message attribute to a node
// addAttr -ln <attribute name> -at "message" <nodeName>;
addAttr -ln leftHand -at "message" troll;
```

```
// add a multi message attribute to a node
// addAttr -ln <attributeName> -at "message" -multi -im false <nodeName>;
addAttr -ln exportBones -at "message" -multi -im false troll;
```

- **Connecting to the attribute**

```
// connect to a single message attribute
// connectAttr -force <node.message> <nodeName.attribute>
connectAttr -force leftHandCtrl.message troll.leftHand;

// connect to a multi message attribute
// connectAttr -force <node.message> -nextAvailable <nodeName.attribute>
connectAttr -force -nextAvailable torso_1.message troll.exportBones;
connectAttr -force -nextAvailable torso_2.message troll.exportBones;
connectAttr -force -nextAvailable torso_3.message troll.exportBones;
```

- **Listing the connections**

```
// list the connection without the attribute (just return the node name)
// listConnections -plug false -destination false -source true
// <nodeName.attribute>;
listConnections -plug false -destination false -source true troll.leftHand;
// Result: leftHandCtrl //
```

```
// list the connection WITH the attribute
// listConnections -plug true -destination false -source true
// <nodeName.attribute>;
listConnections -plug true -destination false -source true
troll.exportBones;
// Result: torso_1.message torso_2.message torso_3.message //
```

Note: When you use listConnections, the result always comes back as a string array.. even if there's only one element being returned.

III. Orienting Joints

Joint orientation

Joint orientation doesn't seem to get a lot of attention, but it's extremely important.

Maya's joint structure is defined different from other programs, it's not segment based, it's joint based, meaning that a skeleton segment is actually made up of two locations, as apposed to an orientation and a length.

The auto-align tool is handy when first creating joints for making sure they're somewhat aiming at their children, but they don't actually fit the bill when really looking to control a joint structure.

For example, if you're building a characters back and you use the auto-orientation tool, maya re-oriens the joints each time you click the mouse, and doesn't actually draw them all in the same orientation. Also, if you move the joints around the orientation doesn't change.

You can always use the **joint -e -oj xyz** command to re-orient the joints, but it doesn't give you quite the control which is necessary when building complicated characters.

Building a back with standard Maya Joint Orientation

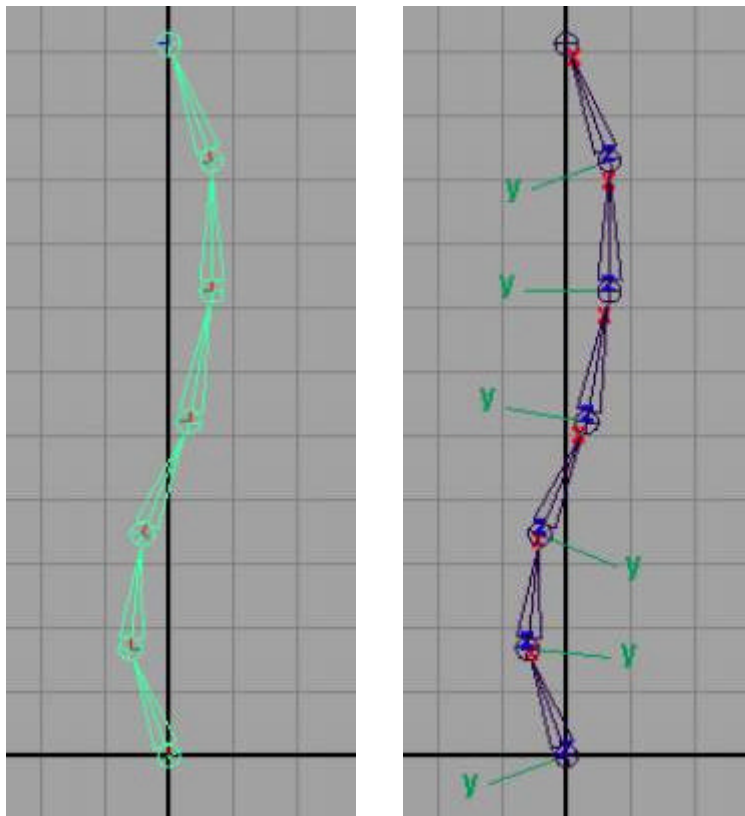
- Select the joint tool.

In the settings, make sure **Auto Joint Orient** is **on**.

- Create a series of joints which represent the s-curve of a back (6 to 8 joints).
- Display the local rotation axes for each of the joints.

You can see that the joints are indeed aiming at their children, there's no consistency as to how the joints are oriented.

(**Display > Component Display > Local Rotation Axis**).



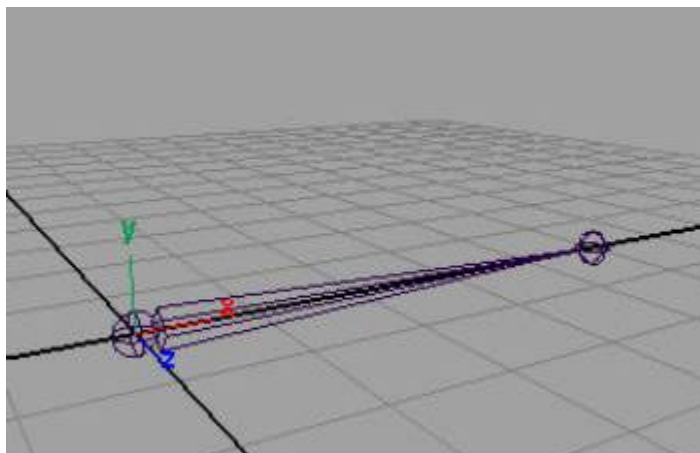
This can be a problem in two areas:

1. If you modify the joint positions, the joints no longer are aiming at their children. (fixable with the **joint -e -orientJoint** command).
2. If you rotate all the joints in Z, some joints rotate forward, others rotate backwards. This can be confusing for animators.

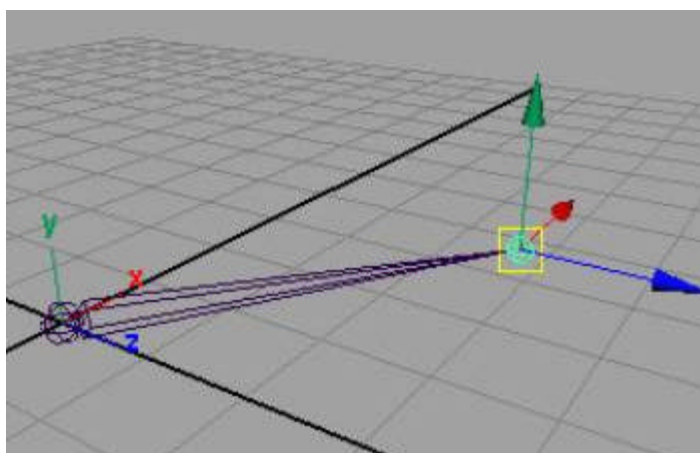
The solution is to come up with a way of re-orienting the joints with control as to what the joint is aiming at, and what it's up vector is.

Manually Re-orienting a Joint in Maya.

- Select the joint tool.
- Create two joints, one at **0, 0, 0**, and the other at **5, 0, 0**;
- Display the local rotation axis for the joint.



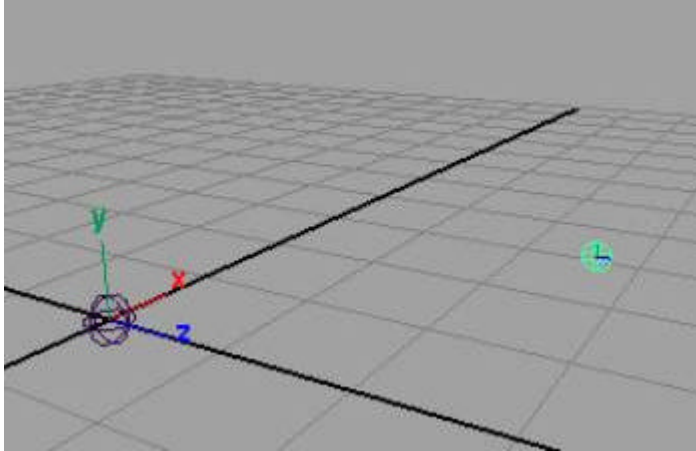
- Move the end joint somewhere off to the side.



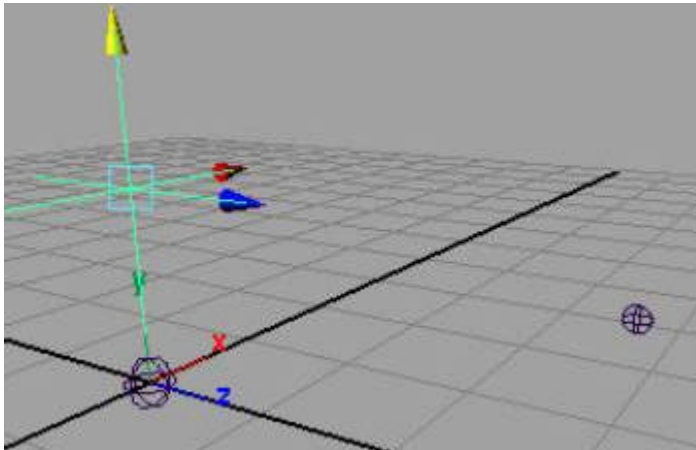
Notice when the first joint is selected, it no longer aims at it's child, and in fact if you rotate it in X, which is what used to cause the joint to spin around it's axis, it no longer does so. This joint has become extremely difficult to control.

To solve this, we're going to manually force joint1 to aim at it's child. Note, in some cases using the joint -e -orientJoint command may work fine. In many cases, however, the technical director will want more control as to the up vector of the joint. The following technique will provide exact control.

- Unparent joint2 from joint1.



- Open the attribute editor for joint1 and make sure the **jointOrient** is set to **0 0 0**, and that rotate is **0 0 0**;
- Create a locator to be used as the upVector. Place is somewhere above joint1.



Now you are going to make an aimConstraint.

- Select **joint2** then **joint1**.
- Select **Constrain > Aim > Option**.

Set the following values:

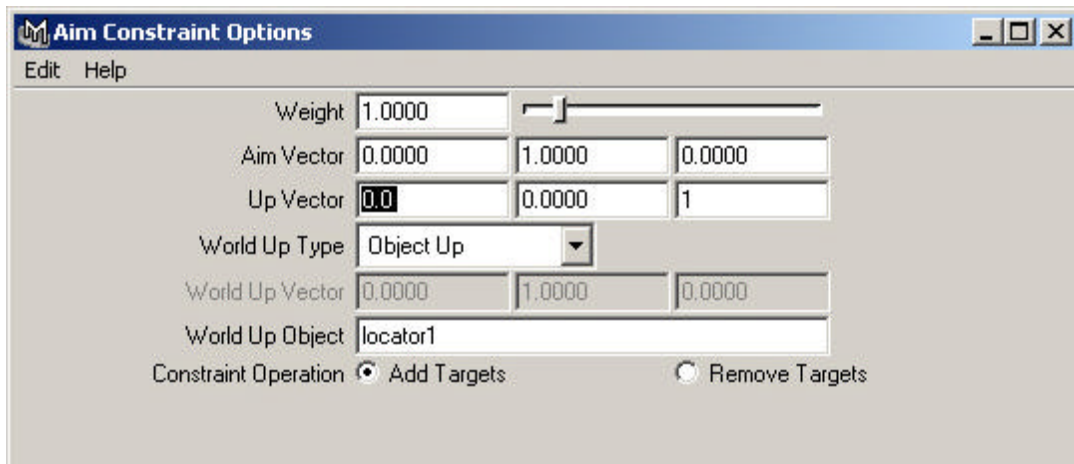
Aim Vector: 0 1 0

Up Vector: 0 0 1

World Up Type: Object Up

World Up Object: locator1

- Click **Add/Remove**.

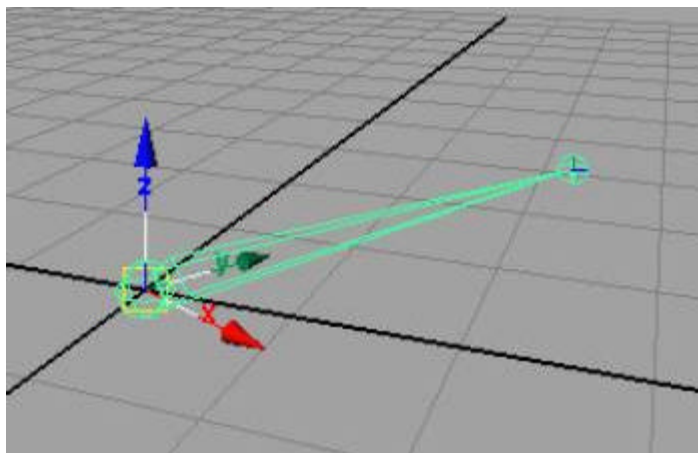


Notice the joint is aiming at the child. If you want to change the upVector for the joint, you can move it wherever you like, until you're happy with the orientation.

- Delete the aimConstraint and the locator.
- Copy the rotation values from joint1 to the jointOrient values.

```
setAttr joint1.jox `getAttr joint1.rx`;  
setAttr joint1.joy `getAttr joint1.ry`;  
setAttr joint1.joz `getAttr joint1.rz`;
```

- Now set all the rotations to 0.
- Parent joint2 to joint1 again. The joint has now been re-oriented to aim at the child joint.



Automatic re-orienting of joint(s) (jsOrientJoint.mel)

Obviously the previous process is too time consuming to perform all the time. Thus, we can use jsOrientJoint for 95% of the cases where it's necessary to re-orient the joints.

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- Recreate the 6 to 10 back joints as shown above.
- Display the local rotation axis for each of the joints.

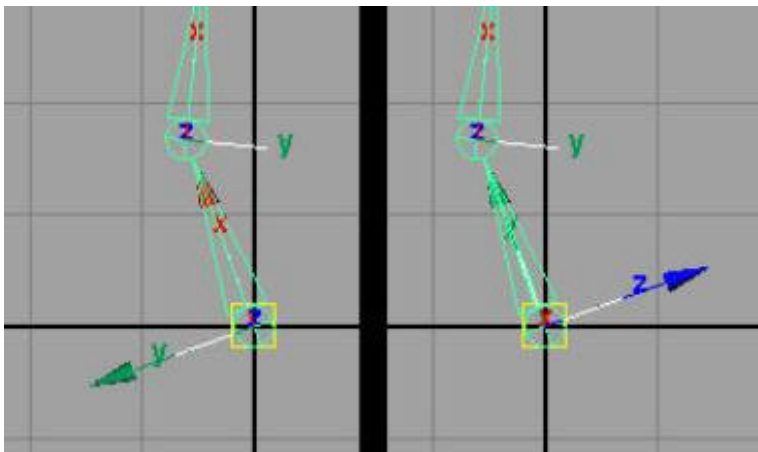


- Bring up the **jsOrientJoint** window by typing jsOrientJoint in the scriptEditor.

This interface has two buttons, one will align the selected joints with their Z axis pointing up, the other with the Z axis pointing down.



- Select the first joint (joint1).
- Click **Z Up**. The joint will re-orient so the Z is aiming up

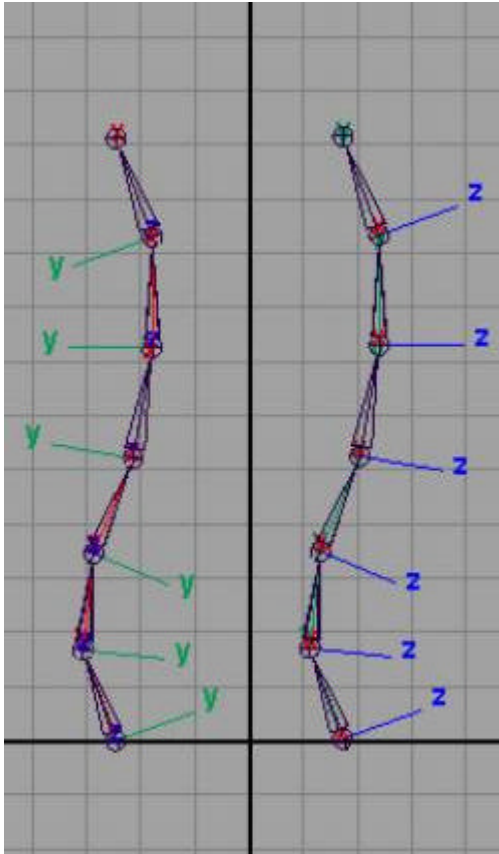


- Select the next joint and this time click **Z Down** to keep the Z axis going the

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same direction.

- Continue this, choosing **Z Up** or **Z Down** until all the joints are aligned the same direction. In the image below, you can see the difference between the orig joints and the newly oriented joints.



IV. Animation Control Concepts

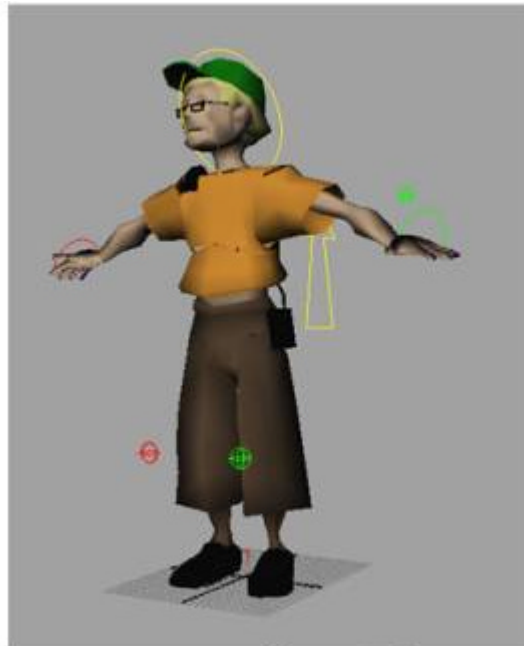
Quite frequently you will be setting up animation rigs for other people to animate, not for yourself. Because of this, it is imperative that you control what the animator can and cannot touch, and give them easily recognizable controls. It's hard enough to animate a convincing creature, let alone spend extra brain power trying to figure out what to pick, where all those extra keys are coming from, and why in the world your creature's left arm is flying off into never-never land.

Iconic Representation

The first step in making things easy to select is giving making the controls easy to understand. If you have a creature that has all the controls visible just as IK handles or selection handles, the screen can become extremely confusing.

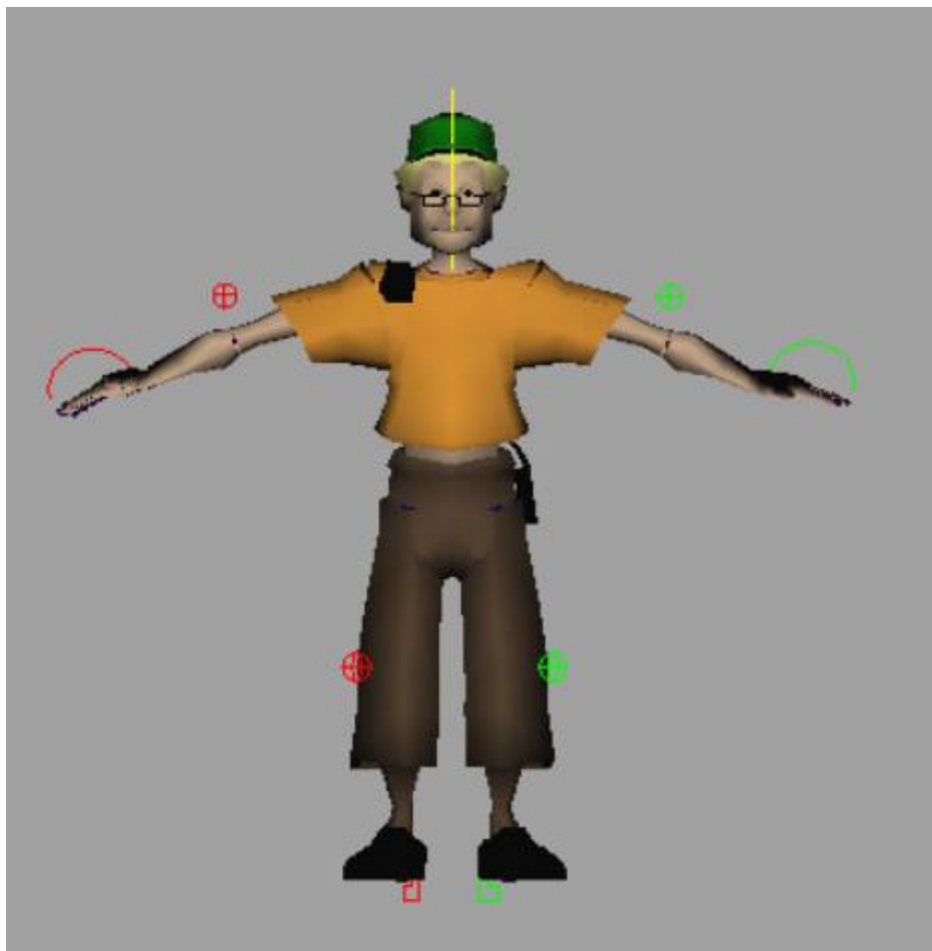


display handles used for controls



curves used for controls

In the images above, you can see that in the setup on the left is a little bit more difficult to understand what's going on. If an animator were asked to pick the full body control, which one would they choose? In the image on the right, we've clearly defined which controls are which. If we keep consistent in making these controls the animator always knows what control is what.



In addition, you'll also notice that the two sides of the controls are different colors. This again helps the animator differentiate between left and right sides of the character.

To change the color of a control, use display layers.

Limiting Selection

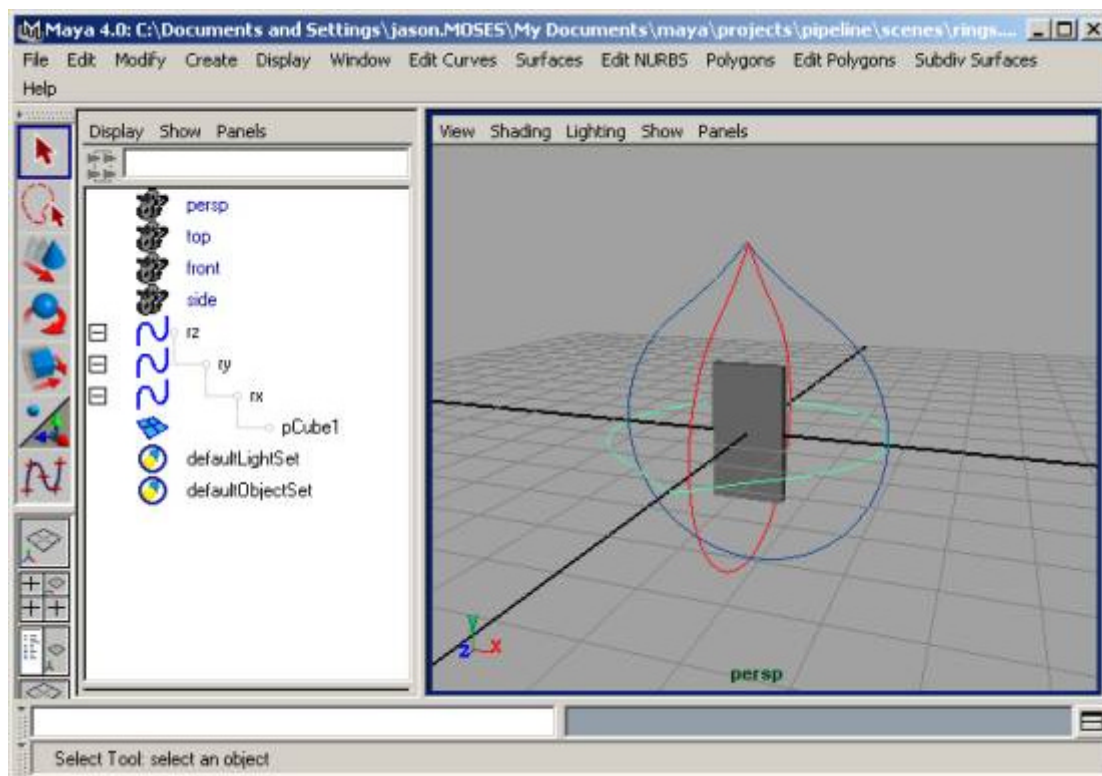
The next step in making sure an animator doesn't grab the wrong controls is limiting what they can select. Take all the objects you don't want the animators touching, and put them in layers which are set to reference mode. This means they're visible, and they show up in shaded mode (unlike templated objects), but you can't select them.

Limiting Keyability

For all the nodes they're animating, it's important to set any attributes you don't want them keying to be non-keyable. (**Window > General Editors > Channel Control**). It does the animators no good to be dealing with five times the number of anim curves they need to.

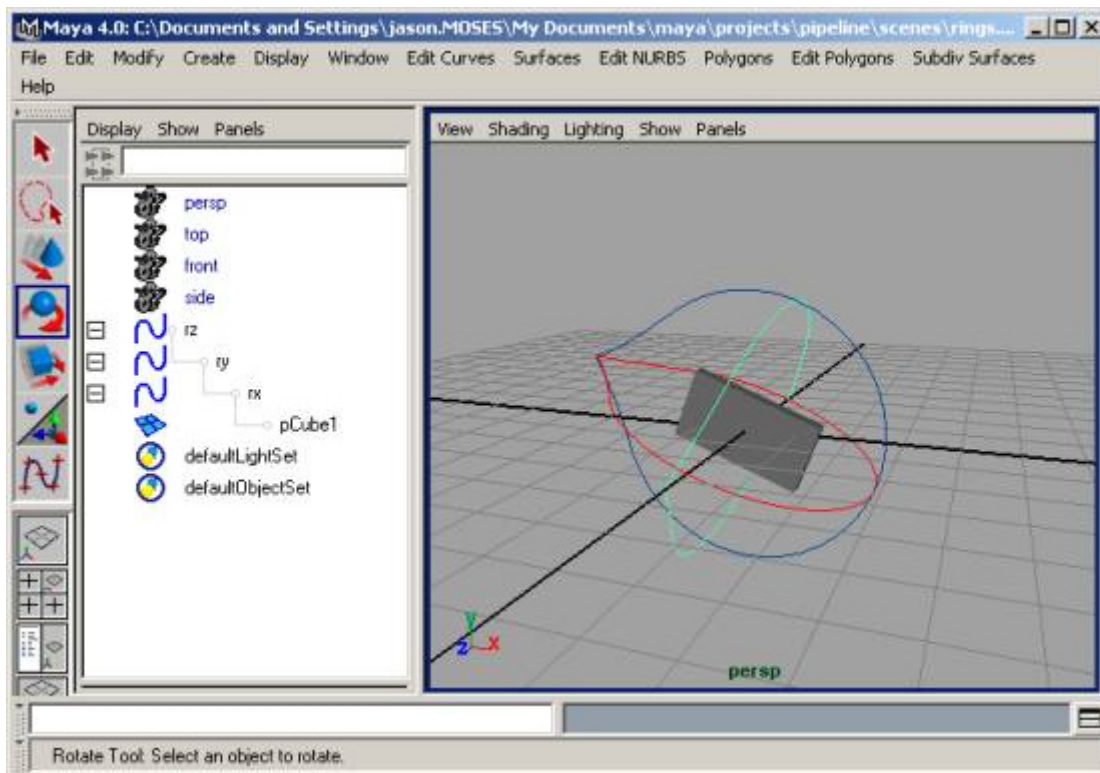
Rotation Order

The next step in making sure the creature can move around is to check the rotation orders on the objects they're animating. This is the order that the rotations get evaluated on a node. An easy way to understand how this works is to actually use separate nodes to control the rotation of an object.

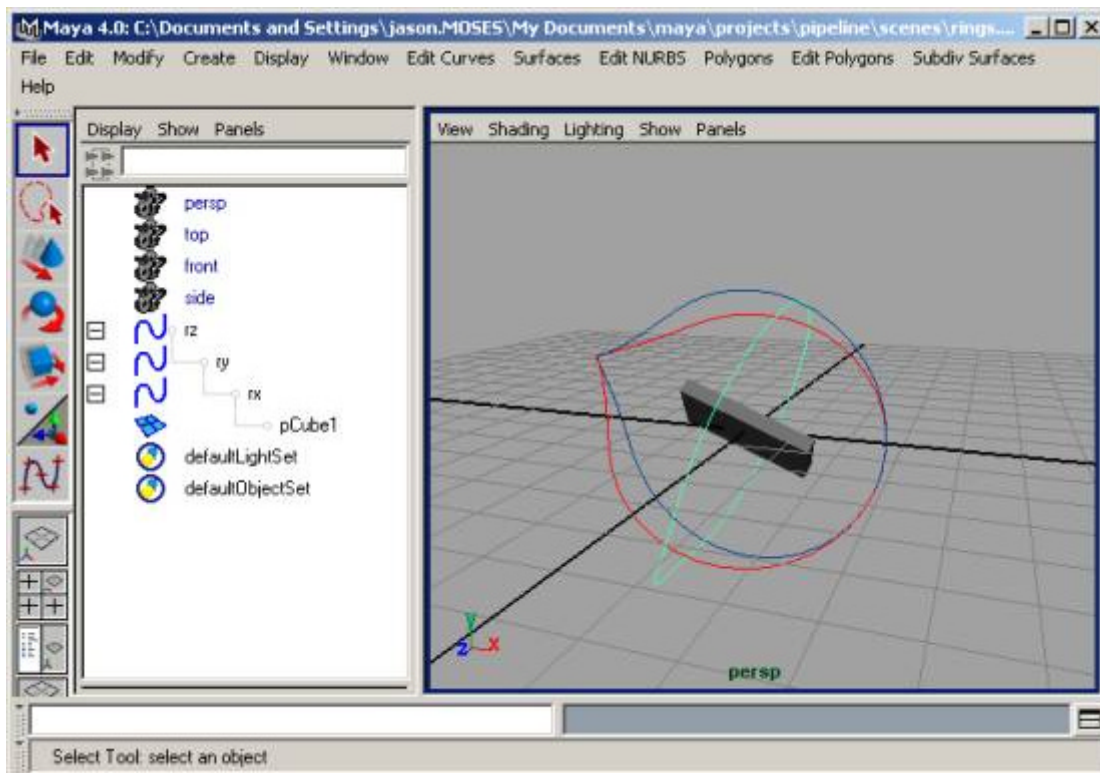


In the image above you can see that we have three different objects available for rotation, rx, ry, and rz. They are currently in the default evaluation order that maya works in (xyz).

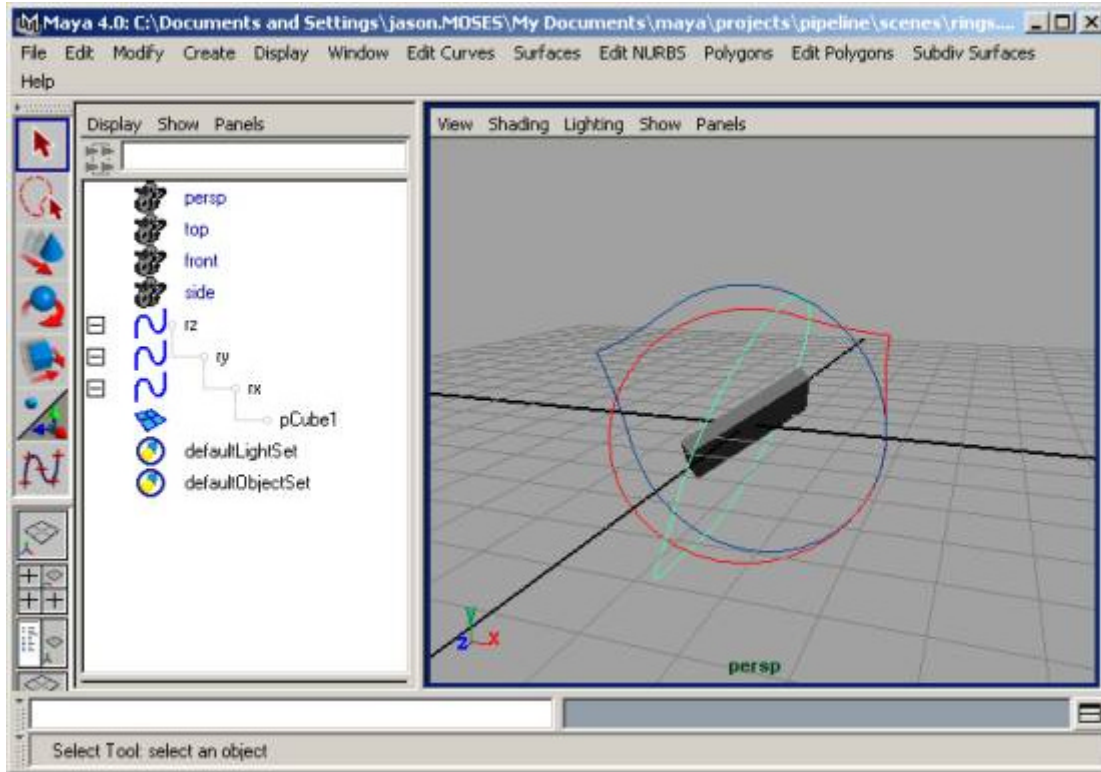
- If we rotate the **rz** you will see the other rings rotate with it.



- Now, if we rotate **ry** you will see that **rz** stays where it is, and **rx** moves.

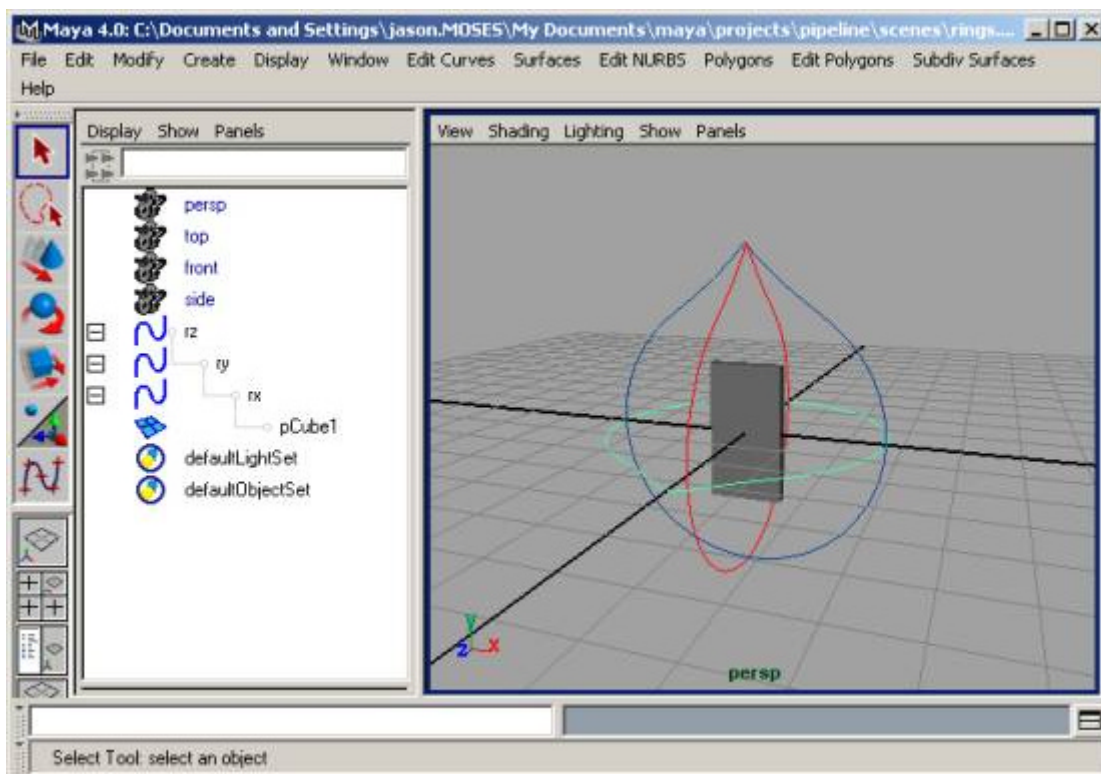


- If we rotate **rx**, both **ry** and **rz** will stay where they are.

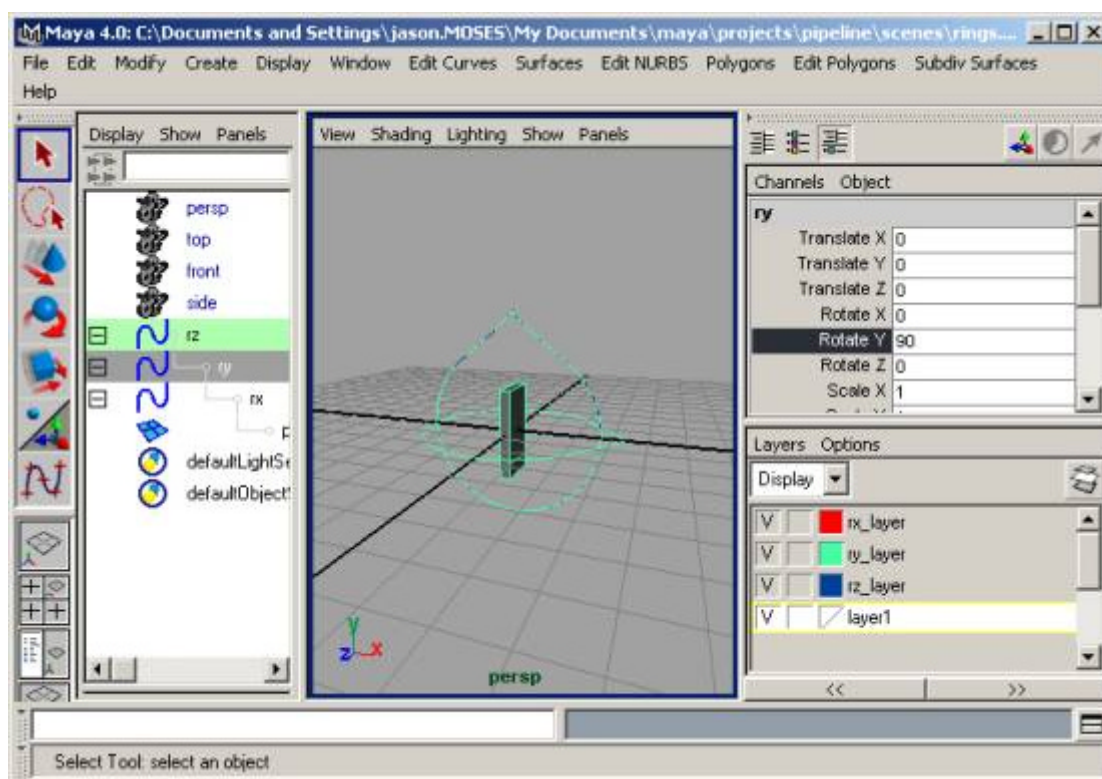


You can see the same result if you use the gimbal mode when selecting an object and rotating it.

If we take a look at a common example of where the default rotation order can screw up a character, let's set the rotation values back to **0 0 0**.

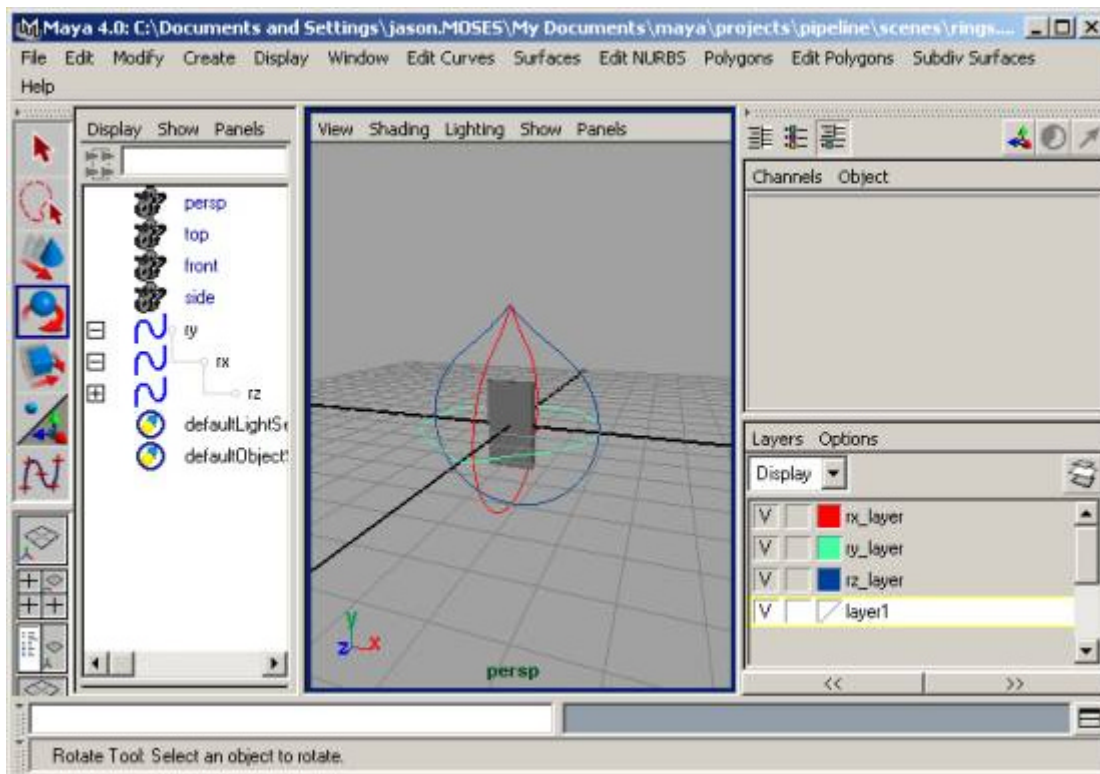


- Now we want to rotate the character around in Y so he's facing the a different direction.

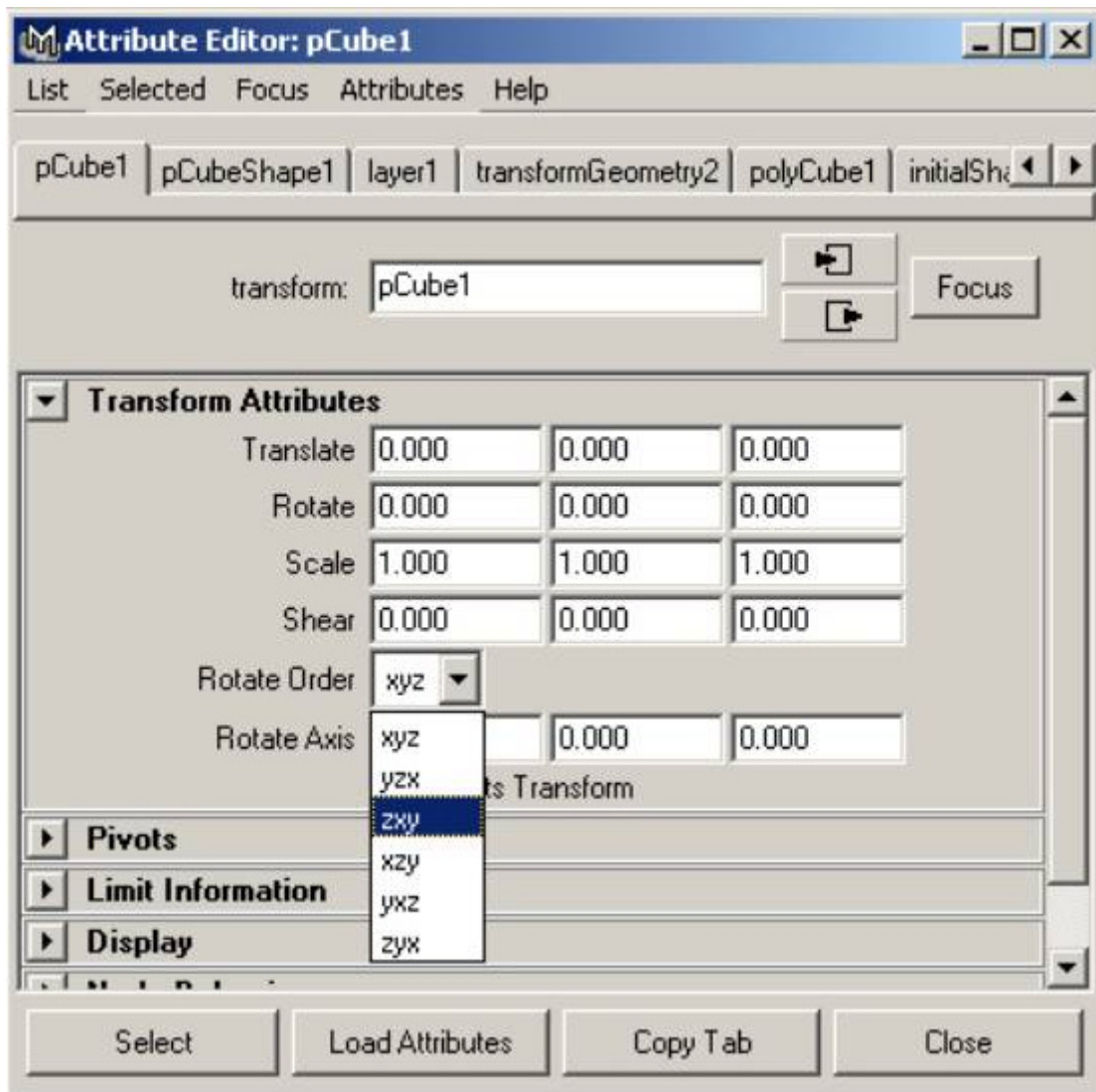


- We just rotated **ry** 90 degrees. You can tell pretty quickly that we're in trouble with rotation orders. Right now the character can keep twisting in Y, and it can bend forward, but it can't lean to the side.

If we decide to change the rotation orders instead so **ry** is evaluated first, then we eliminate the problem of not allowing our creatures to turn around.



- You can do the same thing with changing the rotation order for an object in Maya. In this case, you would change the rotation order in the Attribute editor for the cube to zxy.

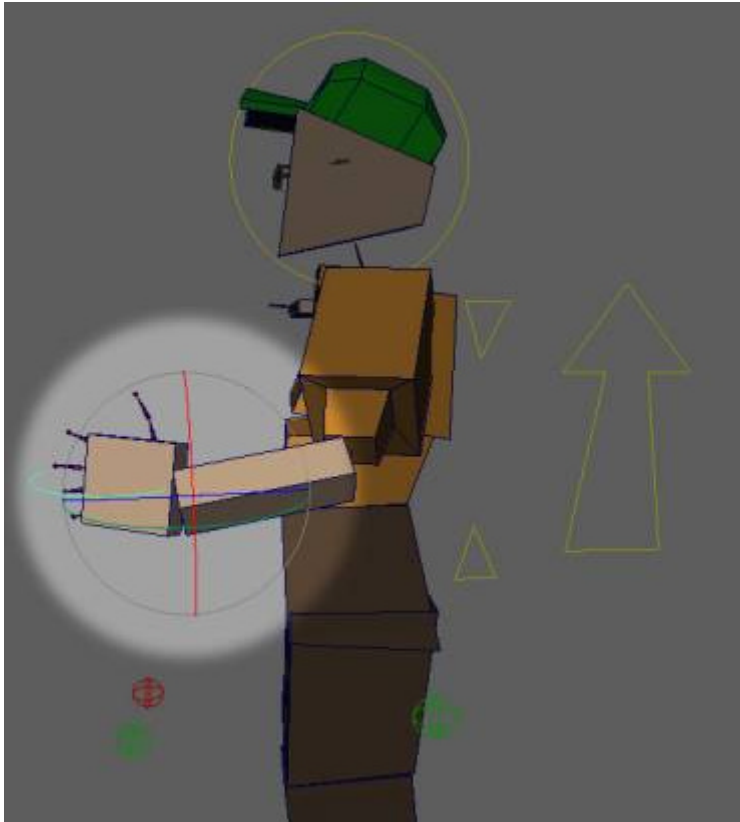


Extra gimbal control

While changing the rotation orders can certainly help remove some of the problems with gimbal locking, it can't remove them 100%. No matter what rotation order you choose for a control, you may run into a gimbal lock problem at some point. (Imagine a character falling from a great height.. if he has to tumble, twist, and spin.. at some point the animator may want him to turn in some direction you haven't planned on.)

Due to this, it's sometimes necessary to add an extra "gimbal" control for the animators to work with.

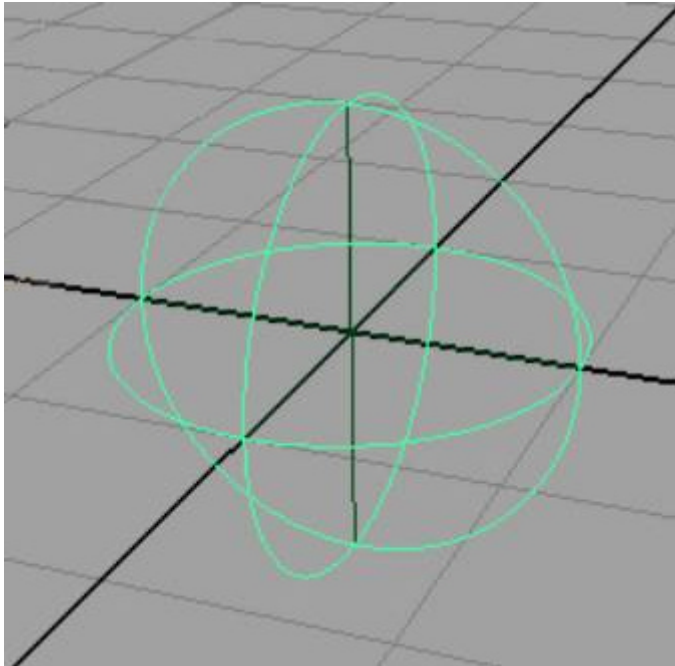
- Load [IrKeithGimbalHand.ma](#)



As you can see, we can't rotate Keith's hand up towards his face due to running out of available rotations.

- We will create an object which the animator can recognize as an extra "gimbal" control. An implicit sphere works well for this.

createNode implicitSphere;

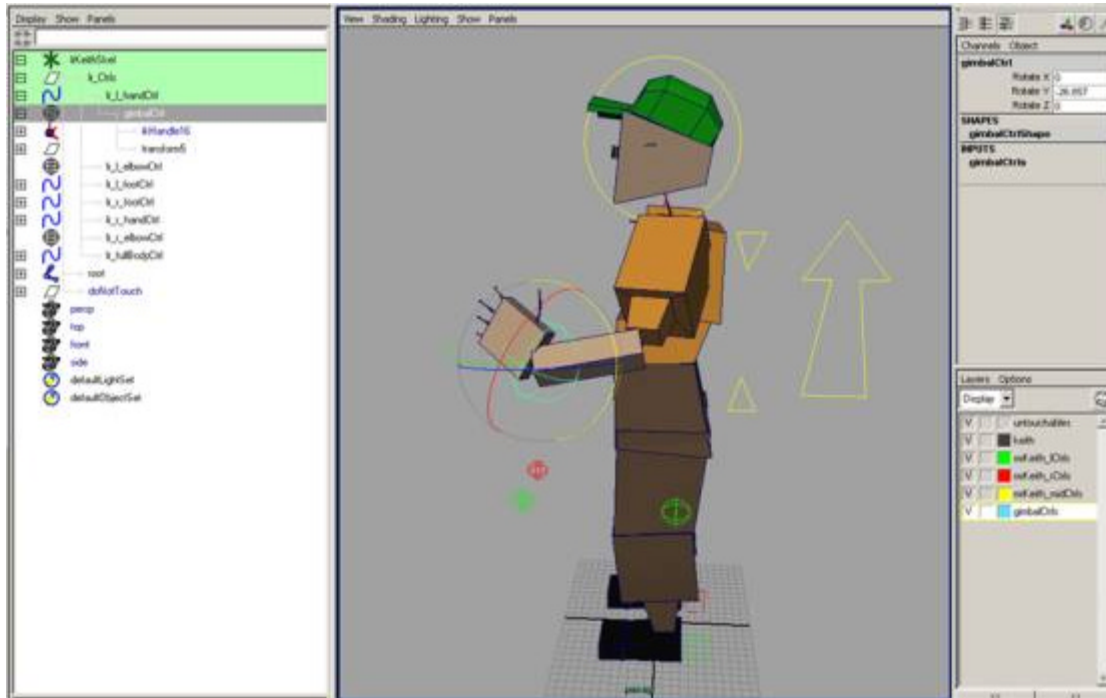


When you create the implicitSphere in this manner, it selects the shape, not the transform.

- Pickwalk up to get the transform.
- Rename it **gimbalCtrl**.
- Parent **gimbalCtrl** under **lr_I_handCtrl**.
- Point and orient constrain the **gimbalCtrl** to **lr_I_handCtrl** to get it in the right position.
- Apply a freezeTransformations.
- Change the gimbalCtrl's radius to make it more visible.

This is accessible through the attribute editor.

- Parent all the objects which were under the orig control to the new **gimbalCtrl**.
- Lock and make unkeyable all translate, scale, and visibility attributes on the gimbalControl.
- If desired, you can make a gimbalCtrl display layer for all the gimbal controls.. that way the animator only sees them when they need to.



It's also highly useful to create a script to generate the gimbal control. This will allow you to add the control to any node the animator has selected, giving them the opportunity to add them only where needed.

// find out what objects are selected

```
string $objs[0];  
$objs = `ls -sl`;
```

// for each object selected, create a gimbal control

```
for ($obj in $objs)  
{
```

// create a gimbal control

```
$gimbalShape = `createNode implicitSphere`;
```

// get the transform

```
$parents = `listRelatives -fullPath -parent $gimbalShape`;  
$gimbalTransform = $parents[0];
```

// rename the gimbal node to match the object

```
$gimbalTransform = `rename $gimbalTransform ($obj + "_gimbal")`;
```

// add a "radius" attribute to the transform and attach it to

// the shape's radius attribute. This will allow us to

// scale the control

```
addAttr -ln "radius" -at double $gimbalTransform;  
setAttr -k 1 ($gimbalTransform + ".radius");  
connectAttr ($gimbalTransform + ".radius") ($gimbalTransform +
```

```
"Shape.radius");
```

```
// move the gimbalTransform to the same place as the control  
// using point and orient constraints  
select $ob $gimbalTransform;
```

```
$cmd = ("pointConstraint");  
$pc = `evalEcho $cmd`;
```

```
$cmd = "orientConstraint";  
$oc = `evalEcho $cmd`;
```

```
// get the children of the orig control  
$children = `listRelatives -f -c -type transform -type joint $ob`;
```

```
// parent the children under the gimbal control  
parent $children $gimbalTransform;
```

```
// parent the $gimbalTransform under the gimbal control, in  
// order to make sure we still get the right name for  
// $gimbalTransform, select it, parent it,  
// and then grab the name of the selected object  
select $gimbalTransform;  
parent $gimbalTransform $ob;  
$sel = `ls -sl`;  
$gimbalTransform = $sel[0];
```

```
// delete the constraints  
delete $oc $pc;
```

```
// lock translate, scale, and visibility of the gimbal control  
string $attrs[] = {"tx", "ty", "tz", "sx", "sy", "sz", "v"};  
for ($at in $attrs)  
{
```

```
    setAttr -l 1 ($gimbalTransform + "." + $at);  
    setAttr -k 0 ($gimbalTransform + "." + $at);
```

```
}
```

```
}
```

```
// select the orig objects  
select $objs;
```

Add Customized PickWalking Tools

Because there is so much to think about when animating, it can be extremely

helpful for the animator to have tools to easily move between controls without having to hunt and peck for what they're going to select, and without having to go to a separate interface.

PickWalking is a great way of doing this (hitting the arrow keys to step to the different controls), however, it is extremely rare that the next node the animator will want is going to be anywhere near the one they have selected in the hierarchy. Thus, you can use **jsPickWalk** to provide that functionality.

jsPickWalk does performs it's navigation through connections as opposed to hierarchy, so there is no limit as to what the next object the animator is going to select.

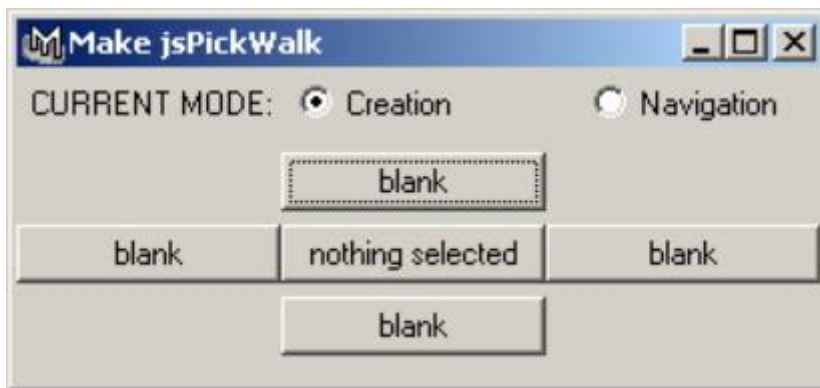
jsPickWalk comes with two different methods of use, definition and navigation. When defining what the animator is going to pickWalk to, you can use the **jsMakePickWalkUI** to easily define what is going to be selected. To navigate, the command **jsPickWalk <dir>** to navigate to either up, down, left, or right, based on the current selection.

Defining the navigation

- Bring up the interface by sourcing **jsPickWalk**, and then executing **jsMakePickWalkUI**

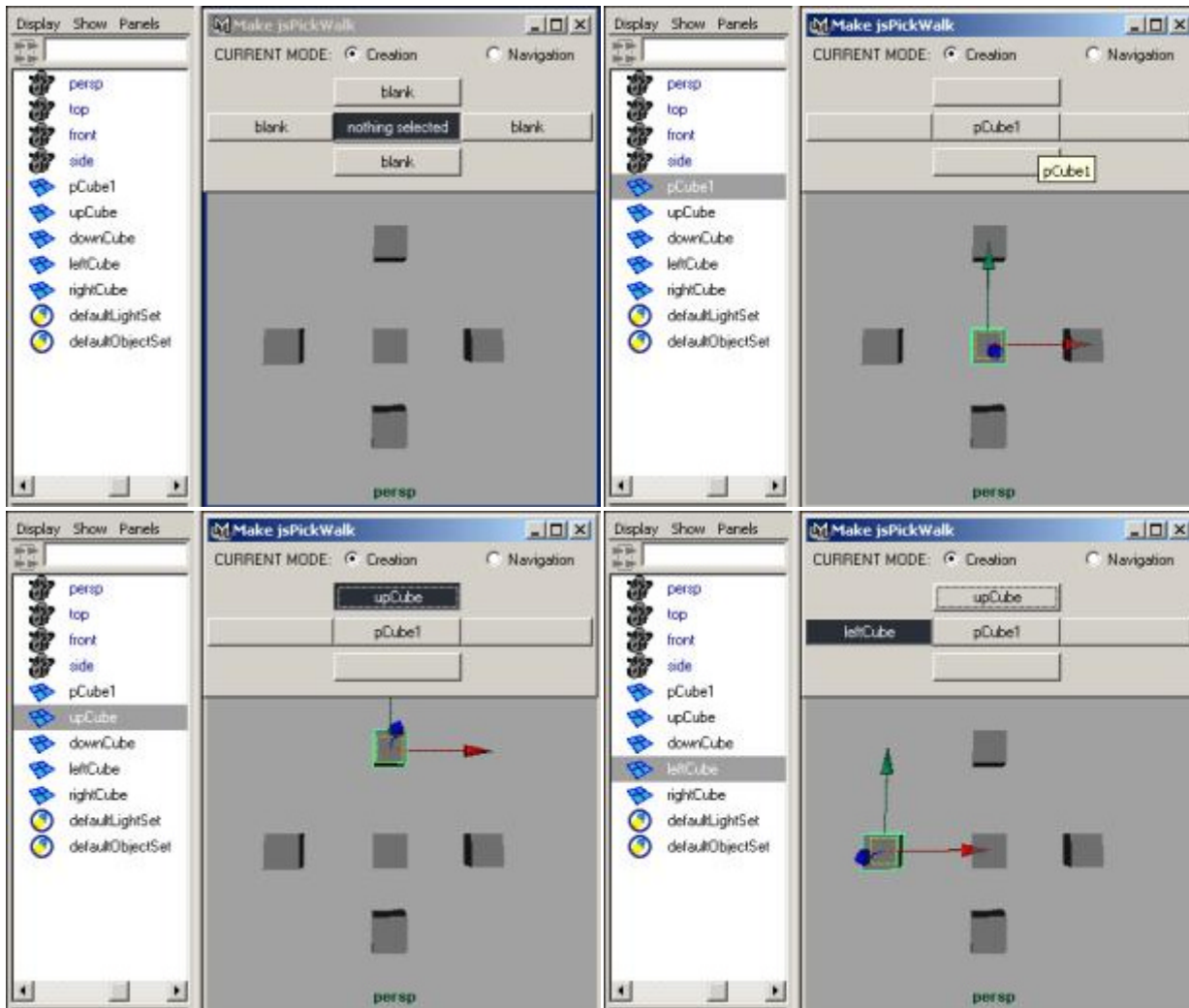
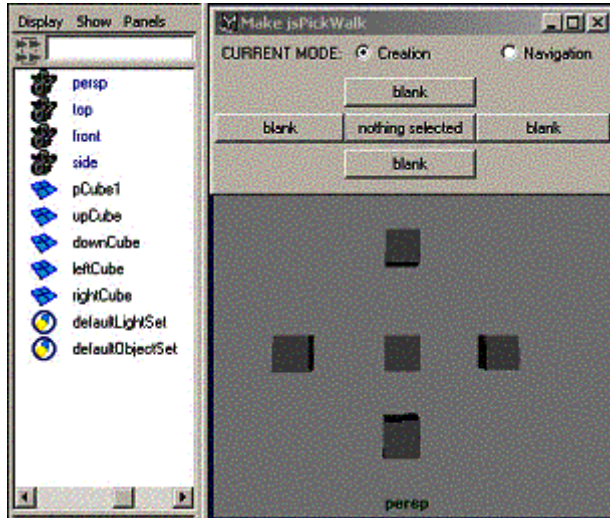
source jsPickWalk; jsMakePickWalkUI;

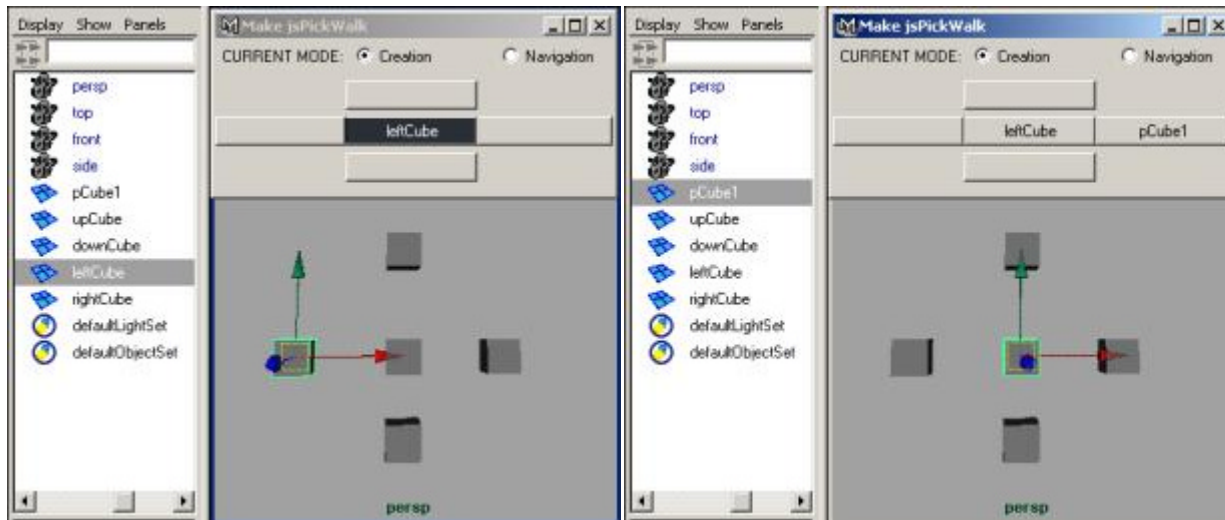
- The interface will come up looking like the following image:



The **Current Mode** section defines what mode the interface is in.

In **Creation** mode, clicking on the **middle** button will put the selected object in the middle, and show the relationships already defined in the **up**, **down**, **left**, and **right** buttons. Selecting another object and clicking on one of those buttons will define that object as the target for pickWalking in that direction.





In **Navigation** mode, clicking on one of the up, down, left or right buttons will place that object in the middle and re-draw the layout based on the newly selected object. You can easily check your navigation this way

Navigating

To navigate, you can either use the interface shown above, or map the navigation to hotkeys using the following commands:

```
jsPickWalk "up";  
jsPickWalk "down";  
jsPickWalk "left";  
jsPickWalk "right";
```

V. Automatic/Keyable Shoulder Solution

Why need one?

- The clavical is an extremely important aspect of the character, which quite often gets overlooked. It's motion is integral to creating realistic characters.
- Because of the tight deadlines, and the amount of revisions that are getting done, reducing the amount of animating that the animator needs to do is extremely beneficial - an automated solution provides an answer to this problem.
- Animators need to have utmost control over what it is they're animating, thus a keyable solution is absolutely necessary.
- Coming up with a solution which works for FK is easy, simply rotate the shoulder joint based on the rotation of the upper arm. However, when you try and do something like that for an IK arm, it doesn't quite work as well. You end up with a cycle. (load shoulderNotWorking.mb to see an example of how this doesn't work)

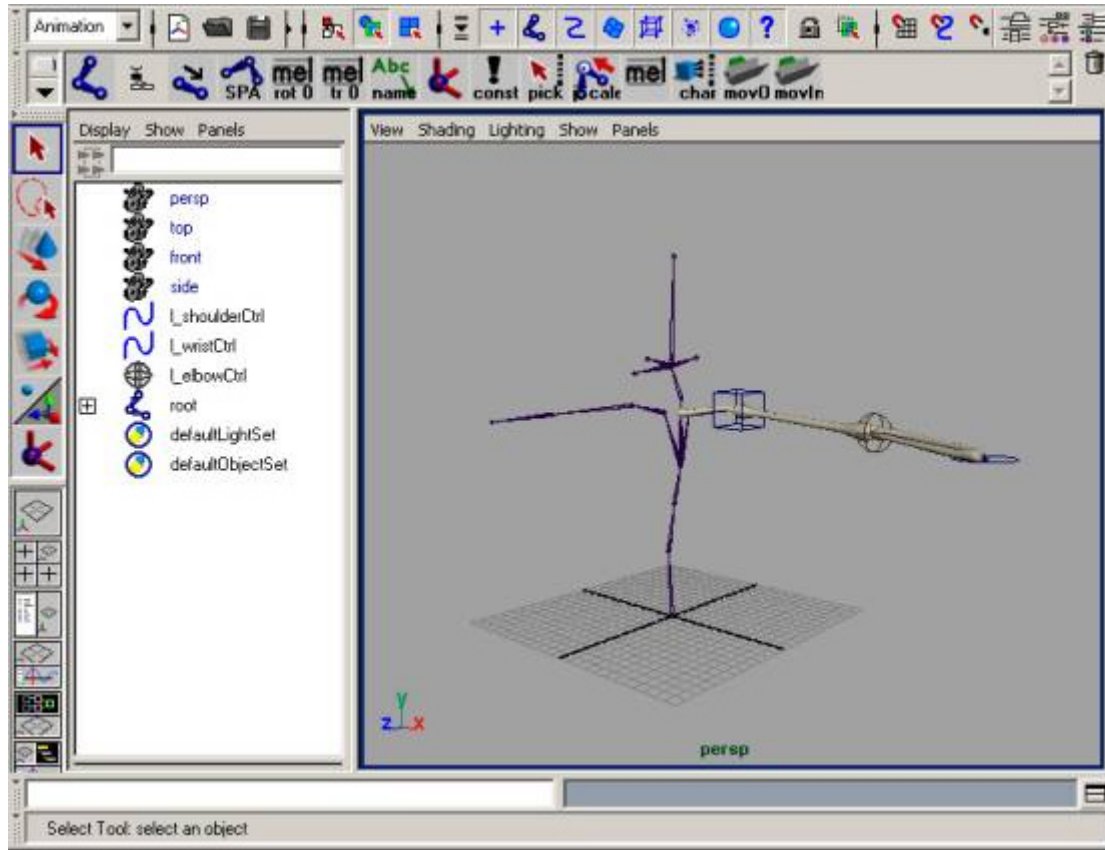
The following solution provides a control which gives the animator the ability to key the automation on and off, animate on TOP of the automation, and even provide a percentage of influence.

Creating the Control Structure

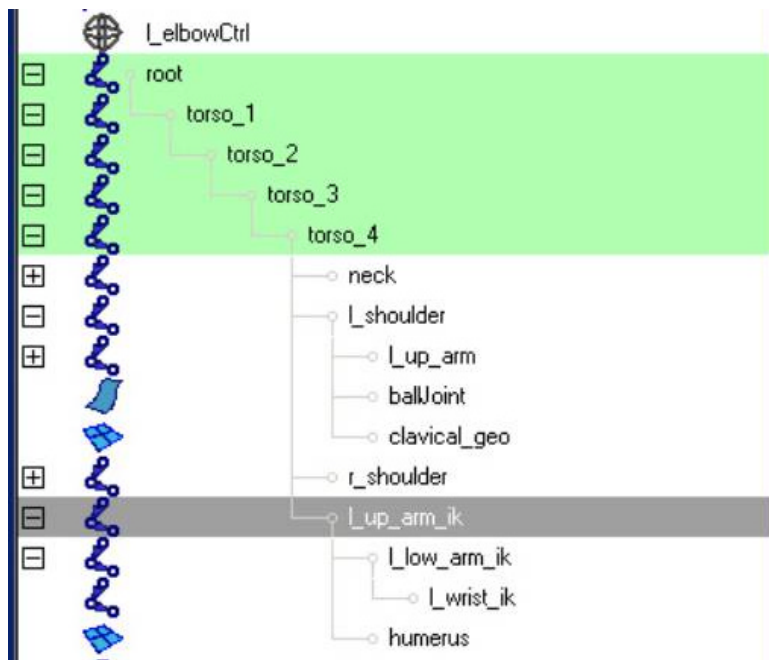
Given a simple torso, clavical, arm structure, create the necessary additional controls.

boneStructure_done.mb
boneStructure_start.mb

Load **boneStructure_start.mb**



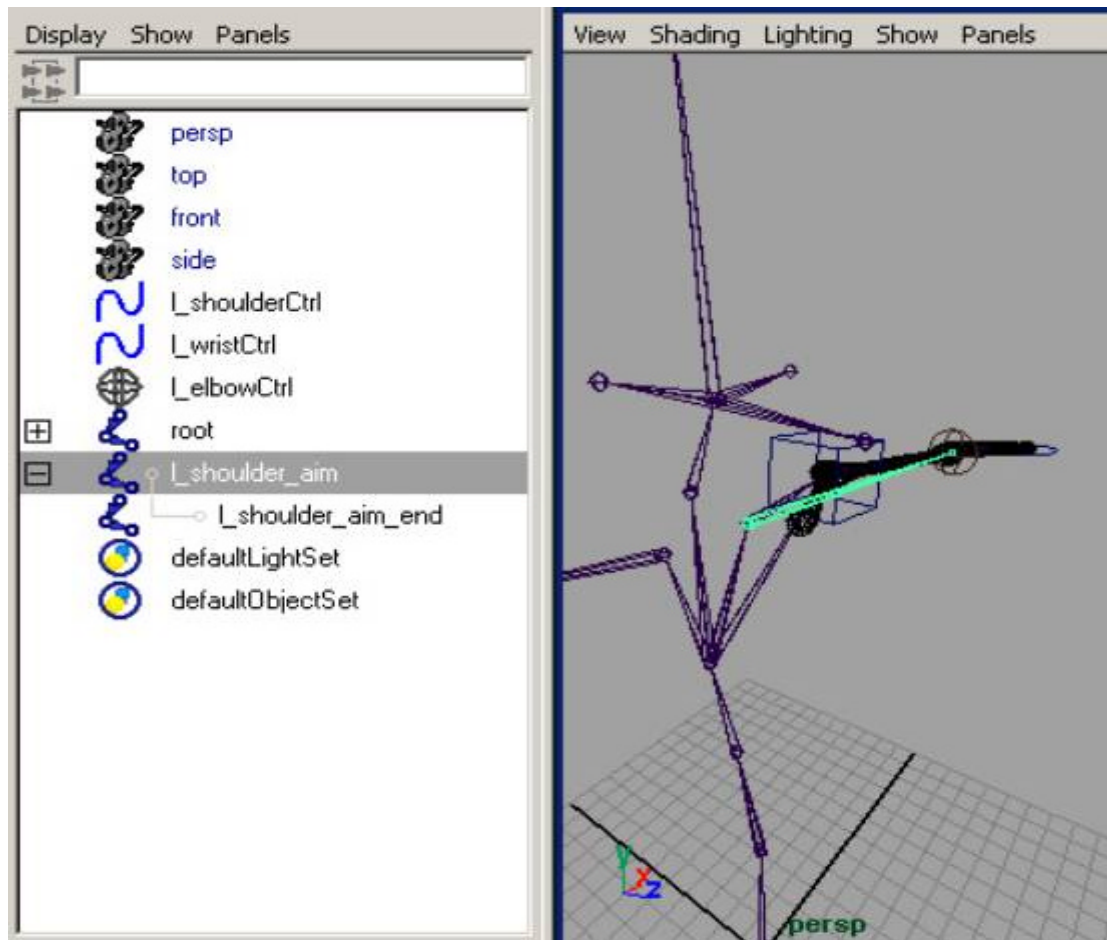
- Duplicate **L_up_arm** and parent the duplicate under **torso_4**.
- Rename the duplicate hierarchy **L_up_arm_ik**, **L_low_arm_ik**, **L_wrist_ik**.
- Delete all the extra geometry under the **L_up_arm_ik** hierarchy.



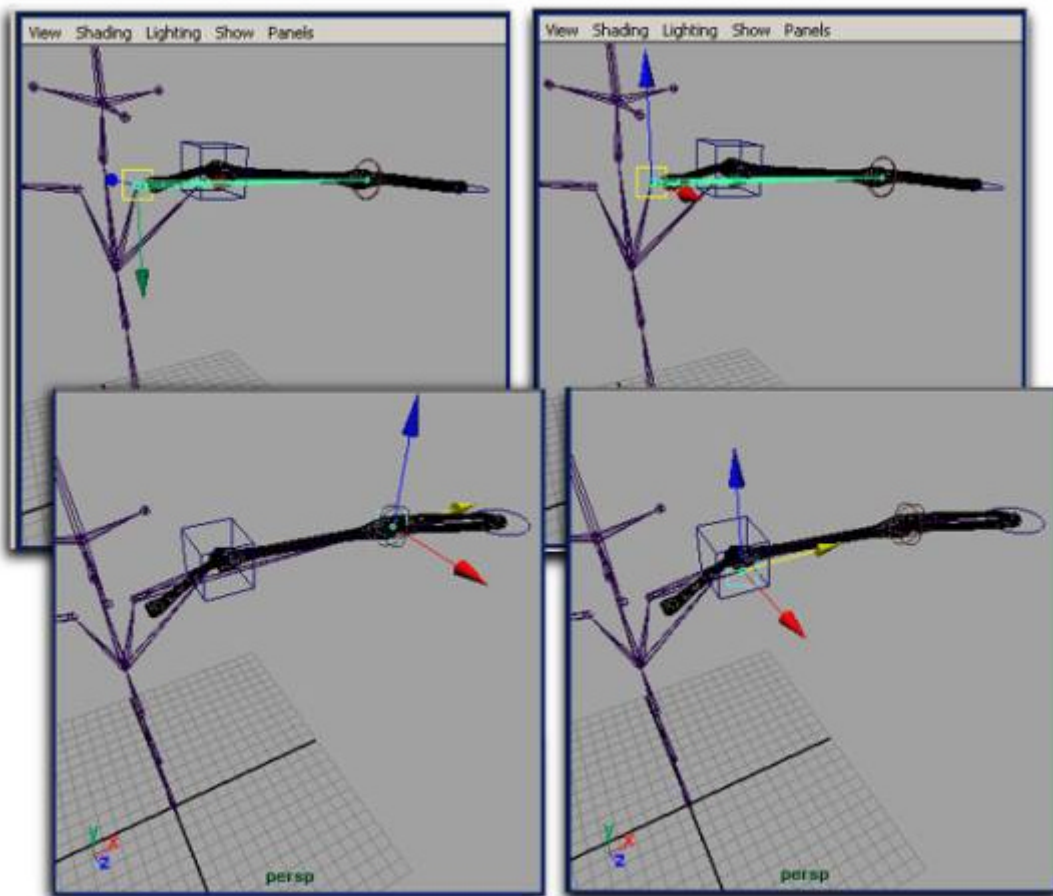
- Create a joint chain which will be used to aim at the **L_low_arm_ik** elbow. It

should start at **I_shoulder**, and end at **I_low_arm_ik**.

- Name these joints **I_shoulder_aim** and **I_shoulder_aim_end**.



- Orient the joint so its **Z** is pointing up using **jsOrientJointUI**, then decrease the ty value of **I_shoulder_aim_end** until it's located roughly around the same location as **I_up_arm** (about 5).



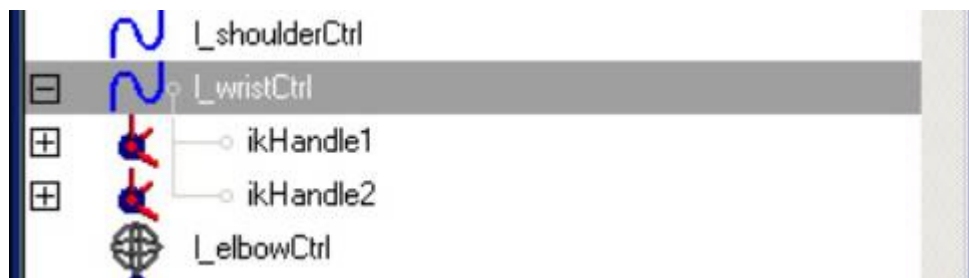
- Parent `I_shoulder_aim` under `torso_4`.

Generate ikHandles for the joints

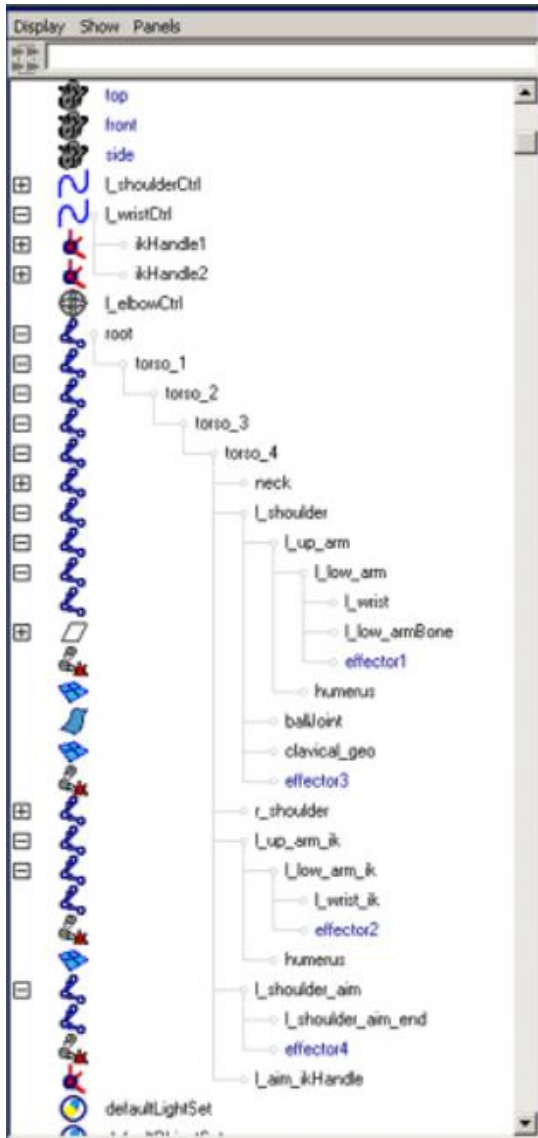
- Choose the IK Handle tool and bring up the option box.

Set the solver type to ikRPsolver.

- Create an ikHandle for `I_up_arm` to `I_wrist`, and another one for `I_up_arm_ik` to `I_wrist_ik`.
- Parent both ikHandles under `I_wristCtrl`.
- Make the `I_elbowCtrl` a poleVectorConstraint for each of the ikHandles.

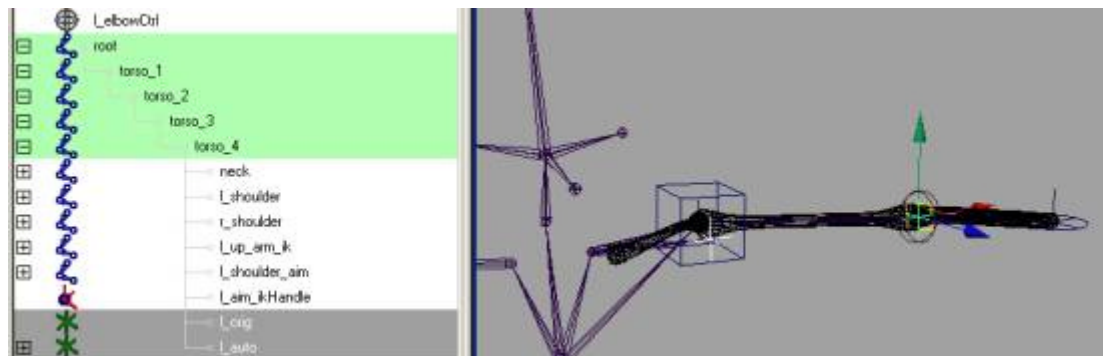


- Bring up the option box for the ikHandle tool again and change the **Solver Type** to **ikSCsolver**.
- Create an ikHandle from **I_shoulder** to **I_up_arm**.
- Parent the ikHandle under **I_shoulderCtrl**.
- Create an ikHandle from **I_shoulder_aim** to **I_shoulder_aim_end**.
- Parent this ikHandle under **torso_4**, and name it **I_aim_ikHandle**.



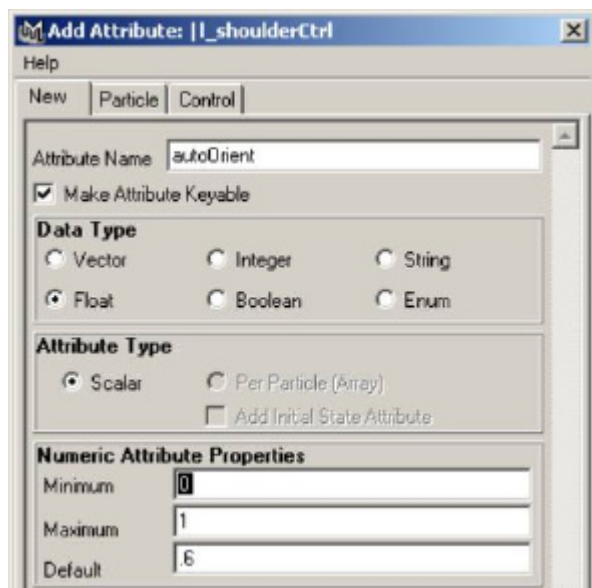
Create the constraints for the **I_aim_ikHandle**.

- Create a locator, name it **I_auto**, and constrain it to **I_low_arm_ik**
- Create another locator, name it **I_orig**. Put it in the same position as **I_shoulder_aim_end** but do not constrain it.
- Parent both locators under **torso_4**.

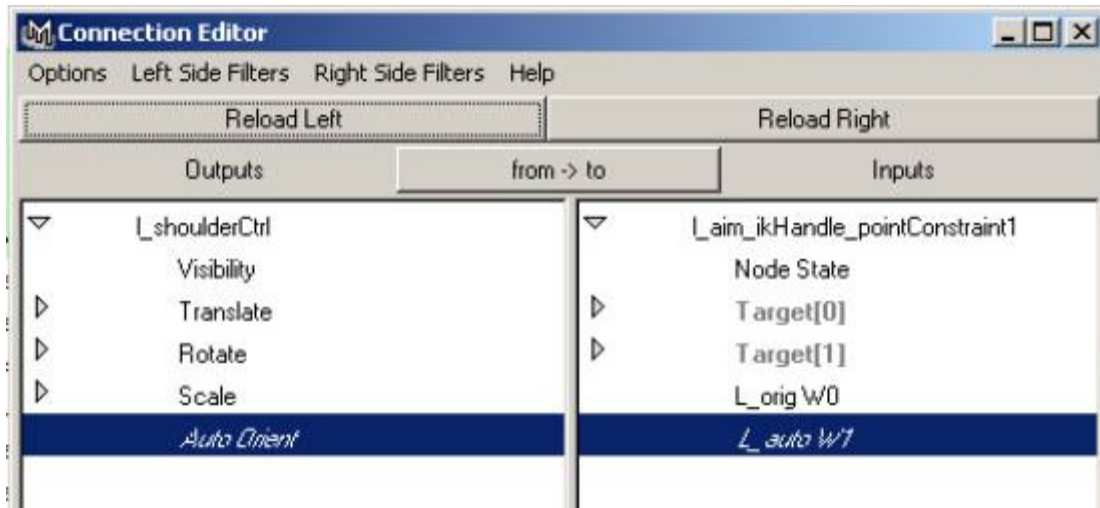


- Select both locators, and select the **l_aim_ikHandle**, and create a pointConstraint.
- Add an attribute to **l_shoulderCtrl** called "**autoOrient**".

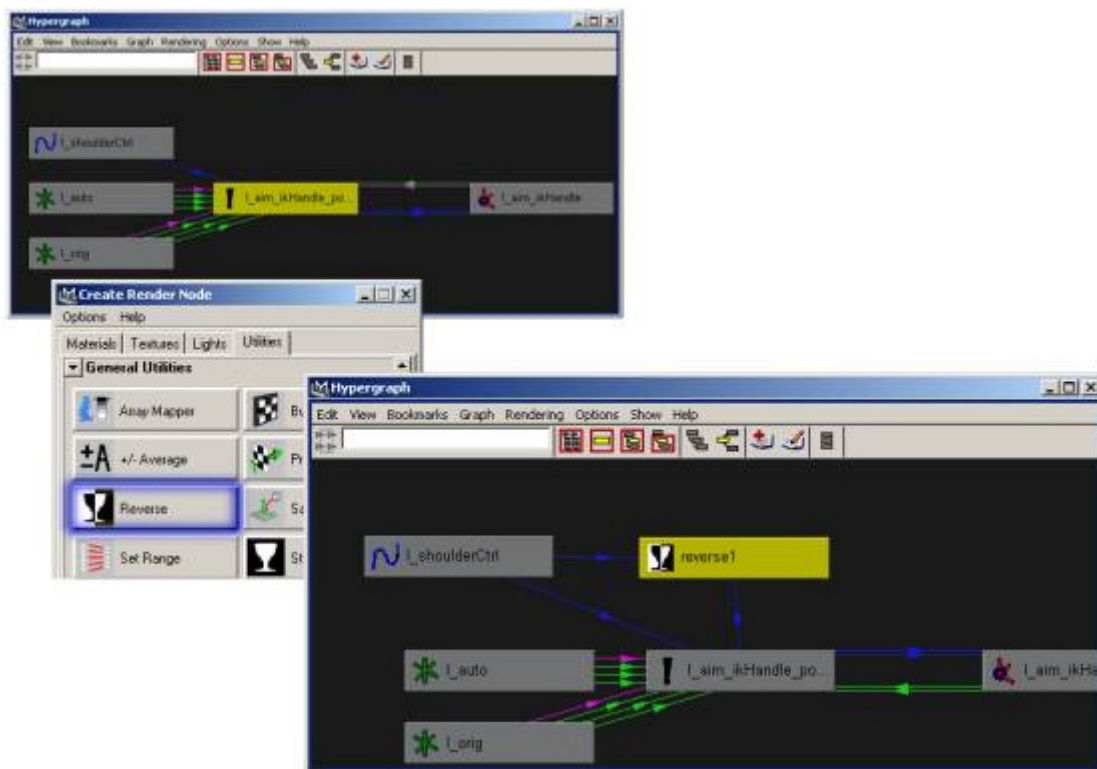
Give it a **Min** value of **0**,
Max of **1**,
Default of **.6**.



- Using the connectionEditor, connect **l_shoulderCtrl.autoOrient** to the pointConstraint's **l_autoW#** attribute.



- In the Hypergraph, create a reverse node, and connect **L_shoulderCtrl.autoOrient** to the **inputX** of that node, then connect the **outputX** to the pointConstraint's **L_origW#** attribute.



- Parent **L_shoulderCtrl** to **L_shoulder_aim**
- Unparent the ikHandle which is under **L_shoulderCtrl**,
- Perform a freezeTransformations on **L_shoulderCtrl**, and re-parent the ikHandle.

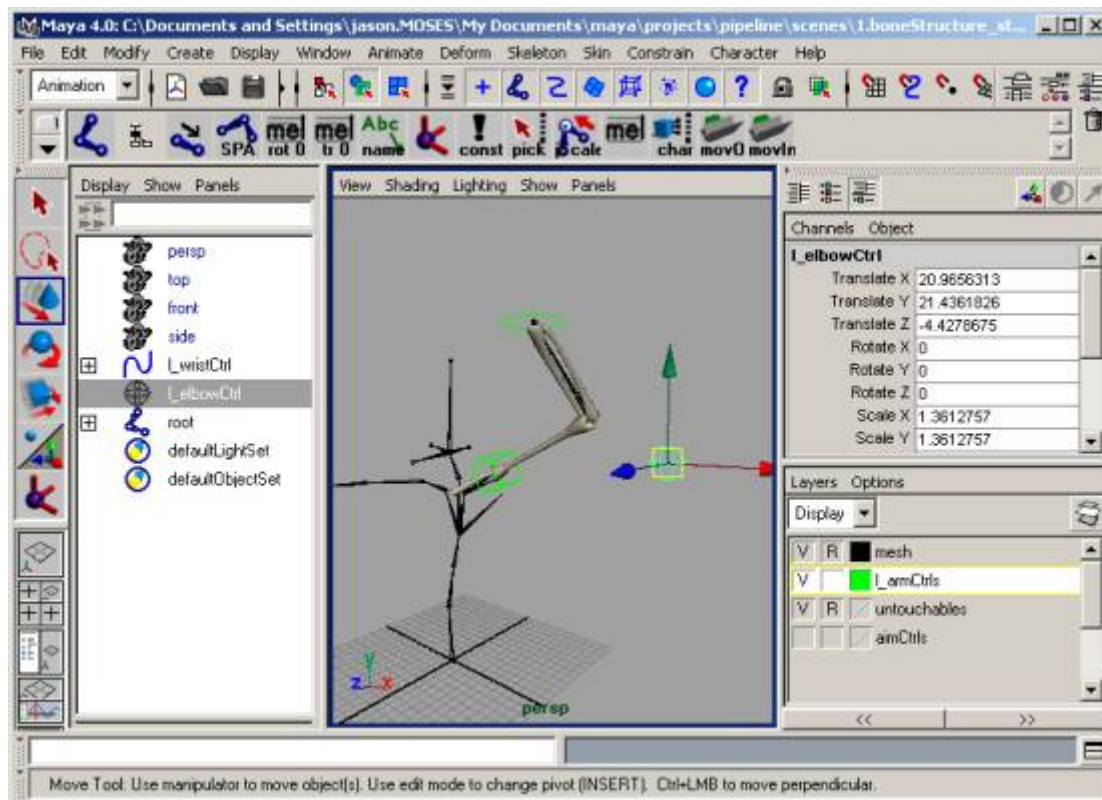
Now when you rotate the handle wrist control around, you can see how the shoulder will follow the motion of the elbow. You can control how much this

following action happens by animating the **autoOrient** attribute on **I_shoulderCtrl**.

Finishing up the Controls

Hide unnecessary nodes & Create appropriate display layers.

- Hide all the ikHandles.
- Hide the two locators.
- Create **I_armCtrls** display layer.
- Create **untouchables** display layer.
- Create **aimCtrls** display layer.
- Select all the joints that the animator shouldn't be touching, and put them in **untouchables**.
- Select **I_shoulder_aim**, **I_shoulder_aim_end**, **I_up_arm_ik**, **I_low_arm_ik**, **I_wrist_ik** and put them in **ikCtrls**.
- Select **I_wristCtrl**, **I_elbowCtrl**, and **I_shoulderCtrl** and put them in **I_armCtrls**.
- Set **untouchables** and **ikCtrls** to reference.
- Set a nice color for **I_armCtrls**.

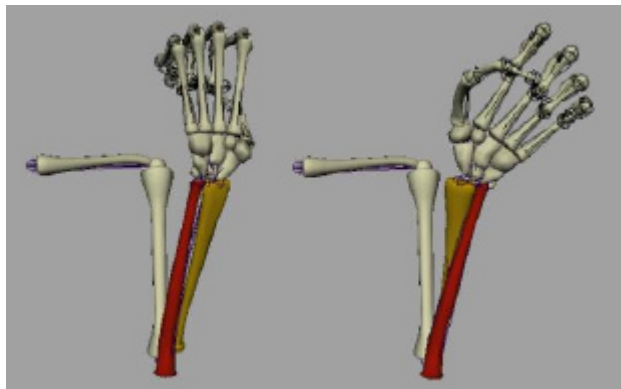


Get rid of Unnecessary Attributes

- Lock and make unkeyable all rotate, scale, and the visibility attribute for **I_elbowCtrl**.

- Lock and make unkeyable scale and visibility for both **I_shoulderCtrl** and **I_wristCtrl**.

VI. REALISTIC FOREARM TWIST



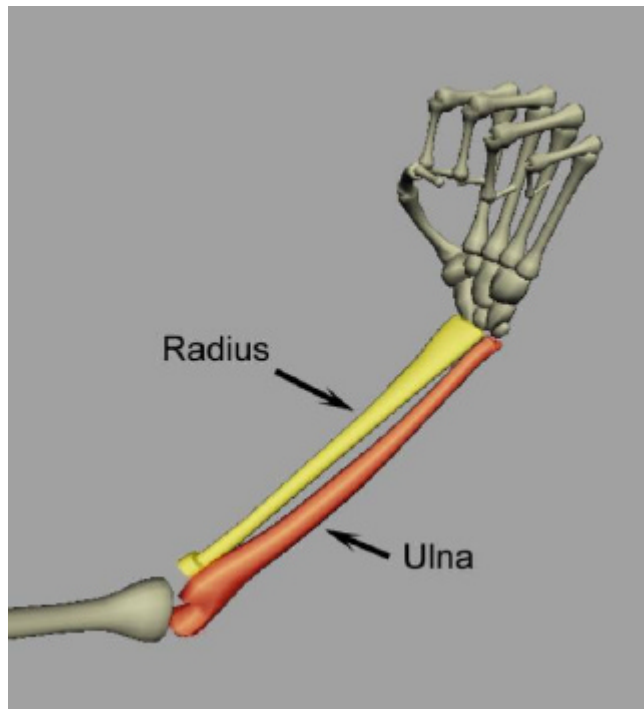
What is a "realistic forearm"

When most people set up a forearm/wrist control in Maya, they do one of two things:

- Forget about doing anything special for their character's forearm and end up with "candy-wrapper" hands.
- Create a joint in the middle of their lower arm and put the twist there, using a lattice deformer to deform the skin.

While the second option will work in many cases, if you're creating a realistic character, it's important to follow what's really happening under the skin.

In actuality, the twist which happens in your forearm is caused by the movement of two bones, the radius and the ulna.



- The **ulna** starts at your elbow, and travels down to the top inside of your wrist (it's that little bump on your wrist where your pinky is).
- The **radius** also starts up near your elbow and reaches down to the other side of your wrist.

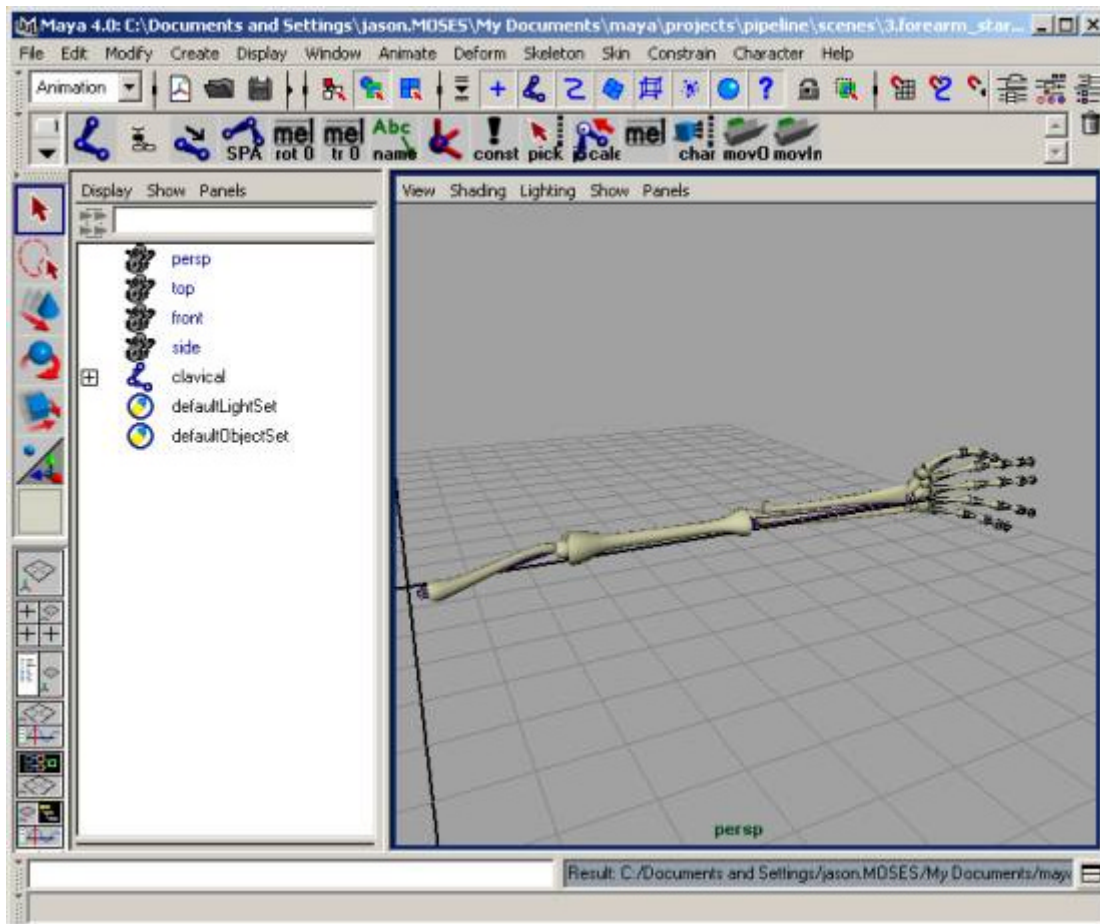
When you twist your wrist, the ulna moves slightly to keep itself connected to the end your wrist, and the radius rotates over the ulna, causing the twisting of the muscles. This is how your elbow stays in one place while you wrist can twist around.

Creating the Control Structure

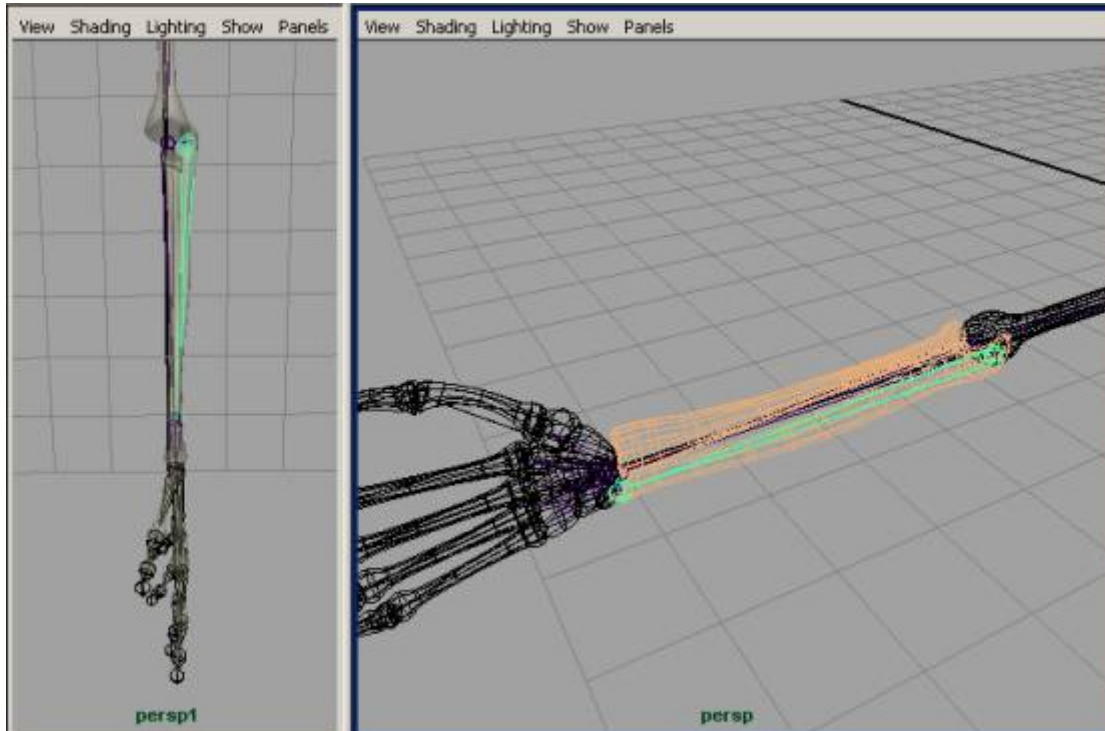
Moving the radius and ulna correctly based on wrist rotation

forearm_start.mb

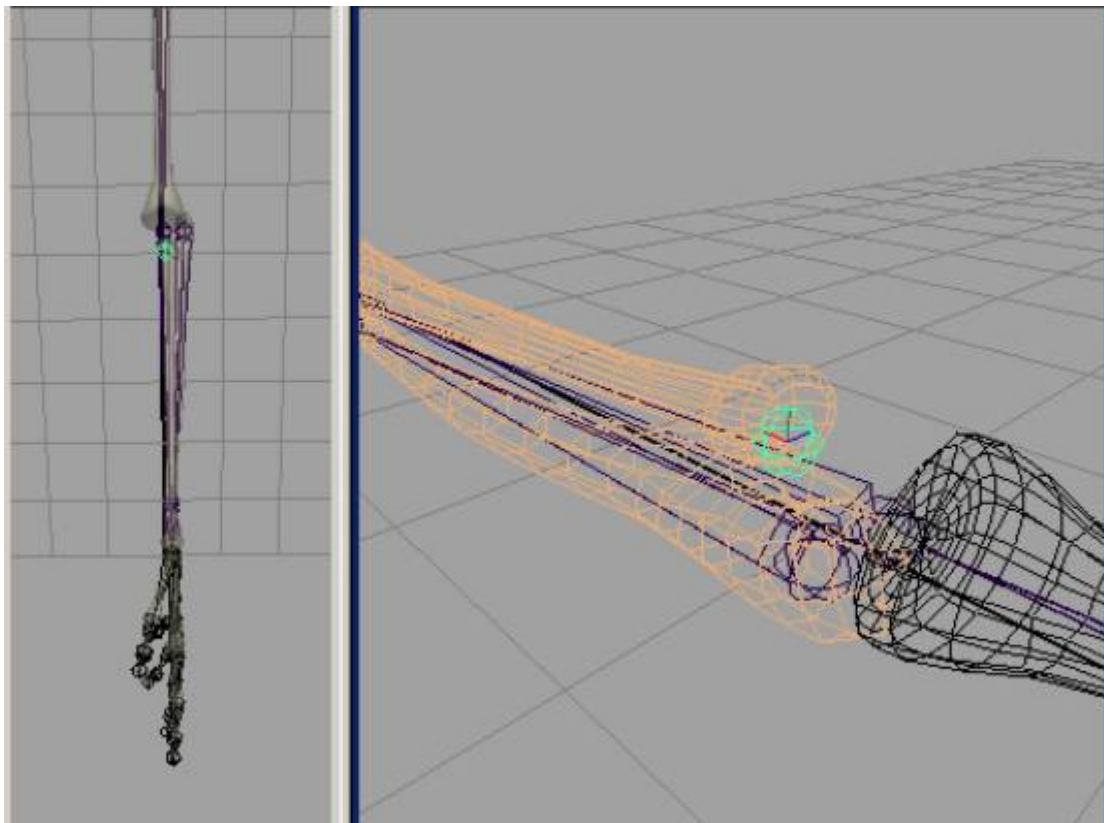
- Load **forearm_start.mb**

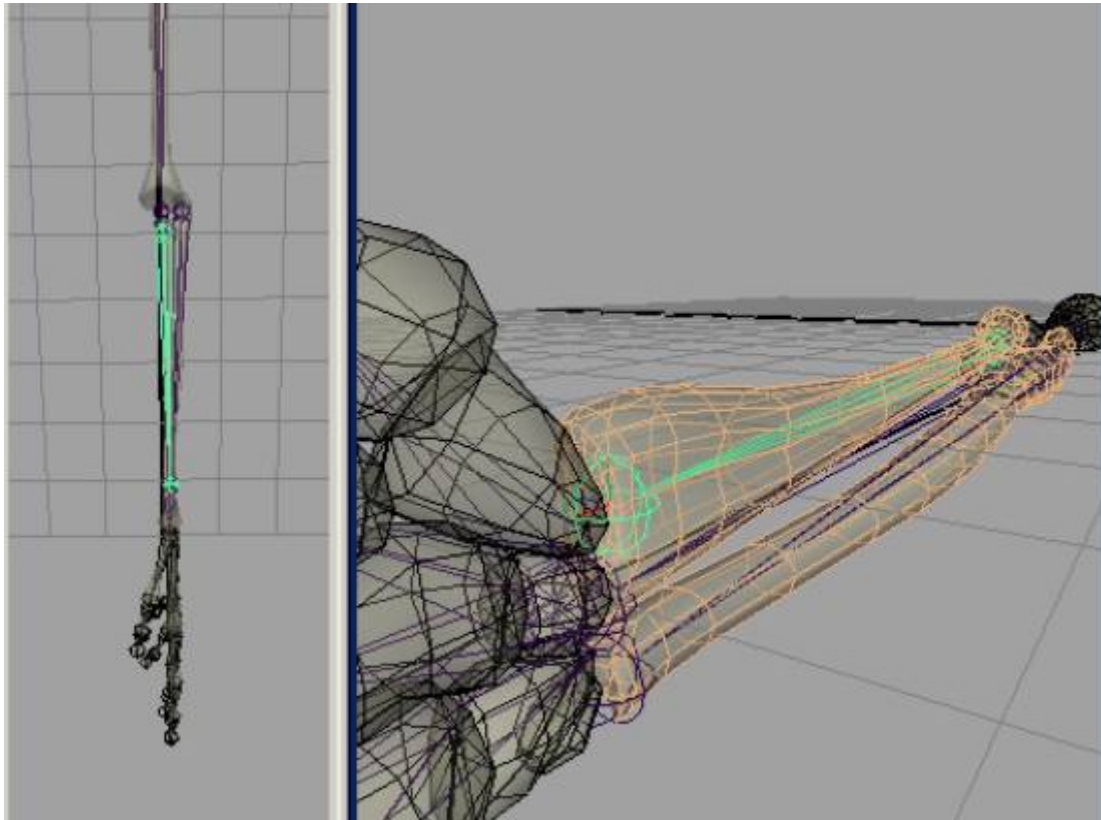


- Create joints for the radius and ulna.
 - Draw a joint chain going from the elbow of the ulna down to the end.
 - Name it **ulna_joint**, and parent the ulna geometry under it.



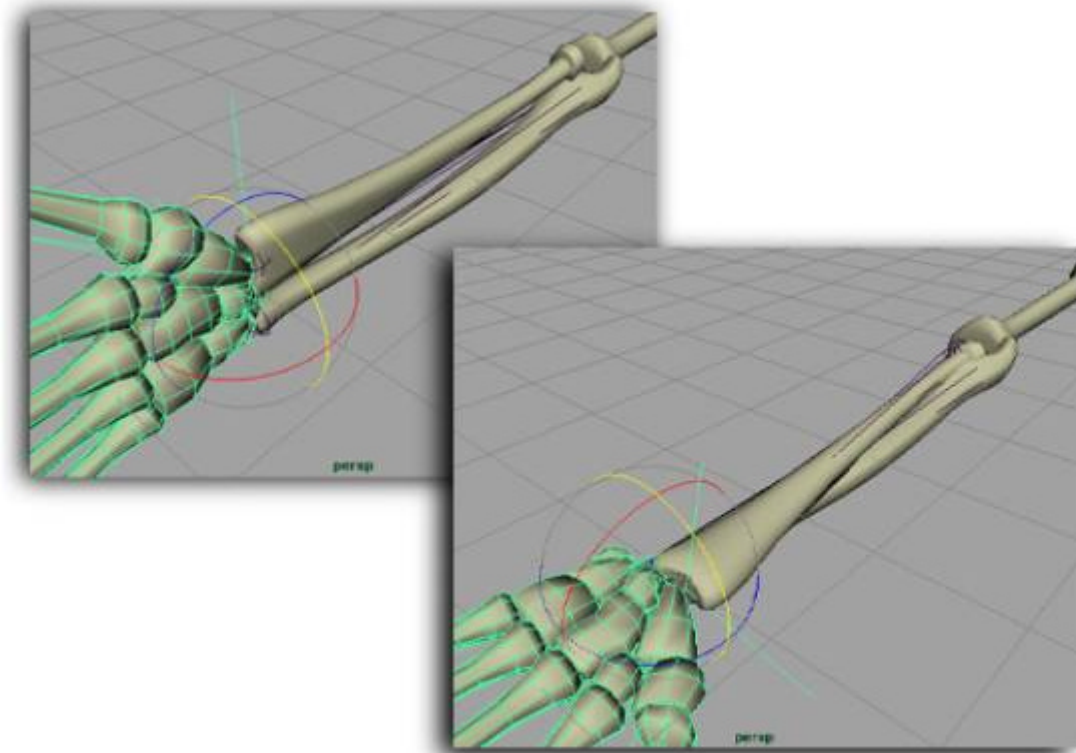
- Draw a chain going from the place where the radius touches the ulna (near the elbow) to the end of the radius.
- Name it **radius_joint**, and parent the radius geometry under it.



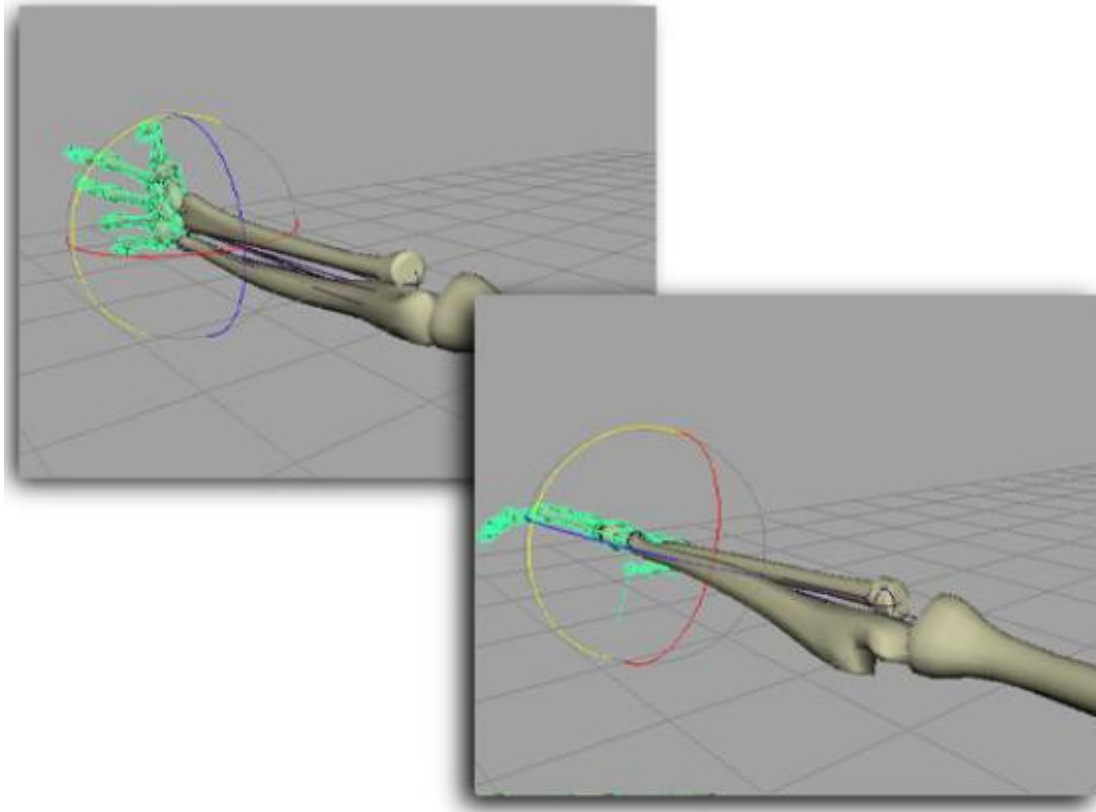


- Move the joints if you need to to get them in the desired places.
- Use **jsOrientJoint** to make sure the joints are all oriented correctly
- Create an ikHandle for the radius joint.
- Parent the ikHandle under wrist.

Now when the wrist rotates, the radius will rotate with it.



- Hide the ikHandle.
- Create an ikHandle for the ulna joint.
- Parent the ikHandle under the wrist.

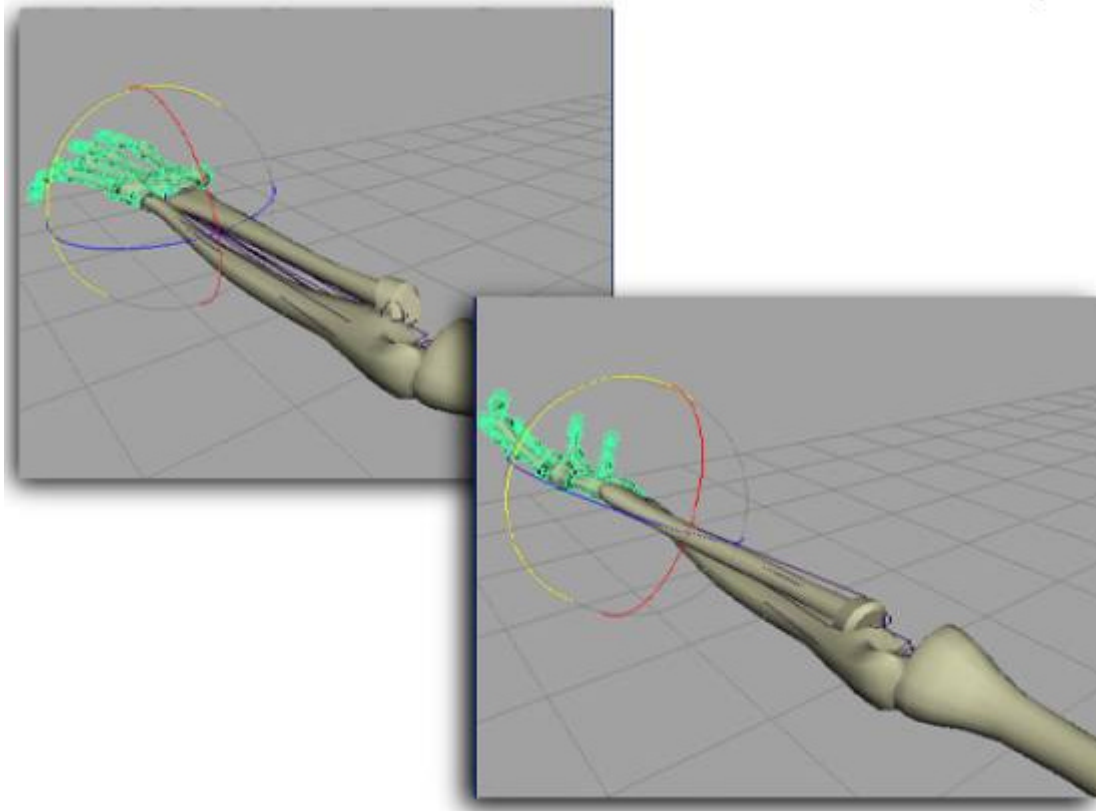


Notice when the wrist rotates, the elbow breaks. This is because the ulna doesn't actually twist, it only moves a bit to keep the radius attached.

To keep this from breaking, instead of parenting the ikHandle, we'll point constrain it to a locator in the same place, and then parent the ikHandle under low_arm.

- Create a locator.
- Put it in the same location as the ikHandle
- PointConstrain the ikHandle to the locator.
- Parent the locator under wrist.
- Parent the ikHandle under **low_arm**.
- Hide the locator.

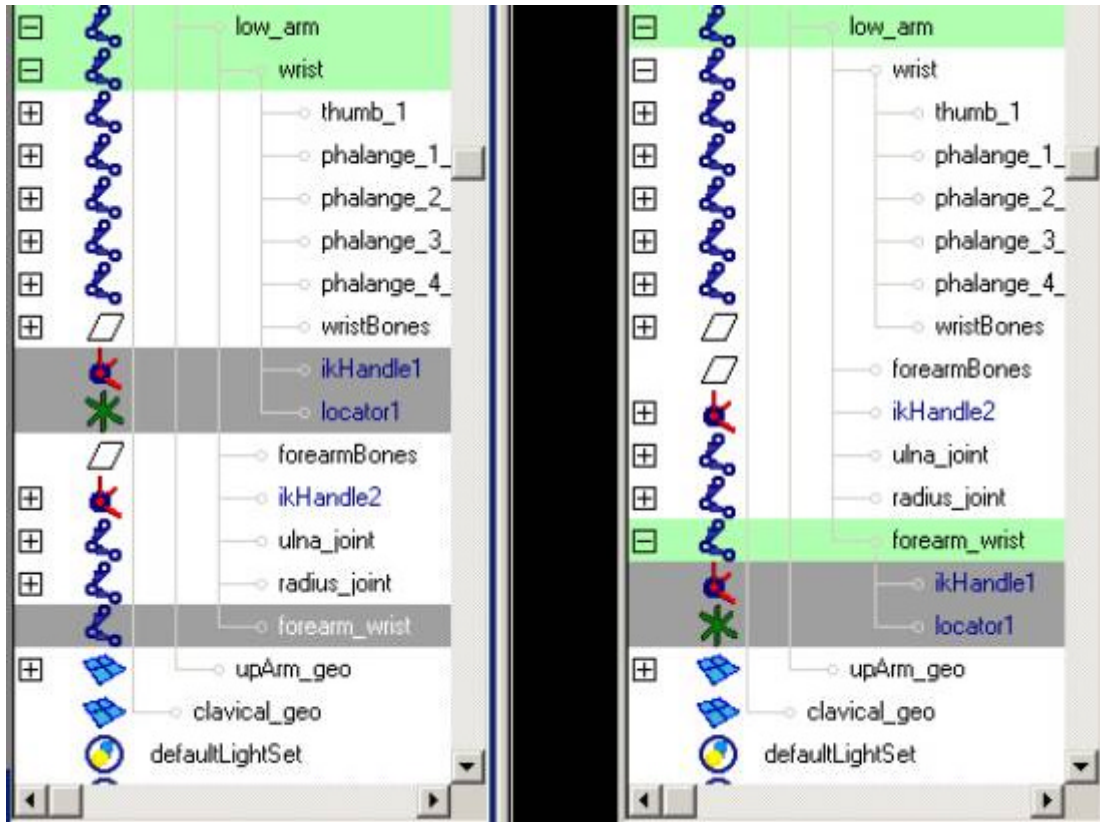
Now rotate the wrist and see how the arm behaves much better.



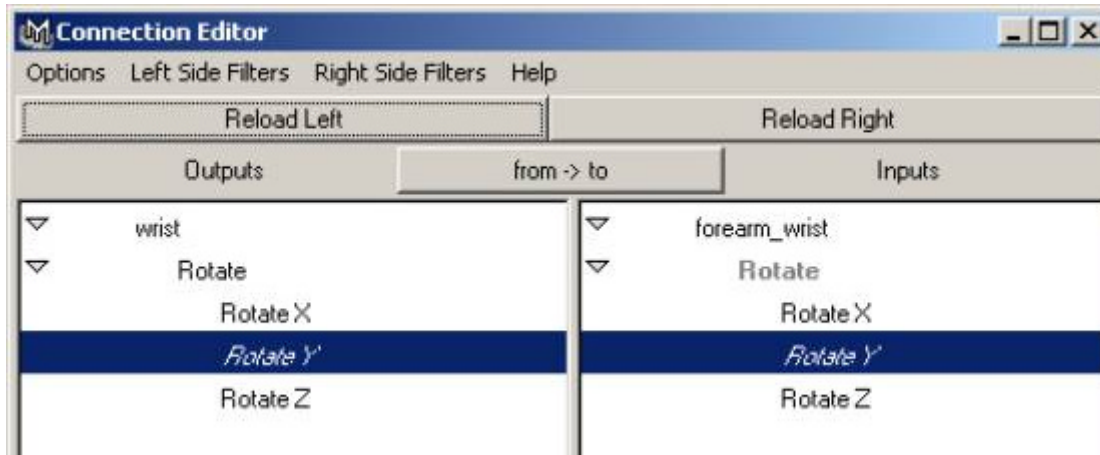
- The next step is to parent the joints under `low_arm`. Now you can rotate `low_arm` and the wrist and everything will behave correctly.

Notice the wrist is working correctly for twisting in **Y**, however, if you twist it in **X** or **Z**, you get a little bit of movement in the forearms. In a real arm, there would be little to no motion here. If you want to replicate that behavior, you need to create another "wrist" to parent the radius and ulna controls under. Then connect the `rotateY` of your animated wrist to the `rotateY` of that new wrist.

- Duplicate **wrist**.
- Name it **forearm_wrist**.
- Delete all the children of the duplicated wrist.
- Parent **ikHandle1** and **locator1** to the **forearm_wrist**.



- Using the connection editor, connect the **rotateY** of wrist to the **rotateY** of forearm_wrist.



- Hide forearm_wrist.

VII. FK/IK BACK SOLUTION

WHY COME UP WITH A BACK SOLUTION?

What does the back need to do?

Some animators like to work in an FK mode of using the back, others prefer IK.

The animator should be able to move the hips and shoulders independently of eachother.

- Example: Animate a character turning around in a circle as if he's going to wrestle. After the blocking is done, you want to be able to keep the shoulders somewhat steady, while allowing for the hips to move independently. To make sure the back is easy to manipulate, it should stretch to meet the root and shoulder controls.

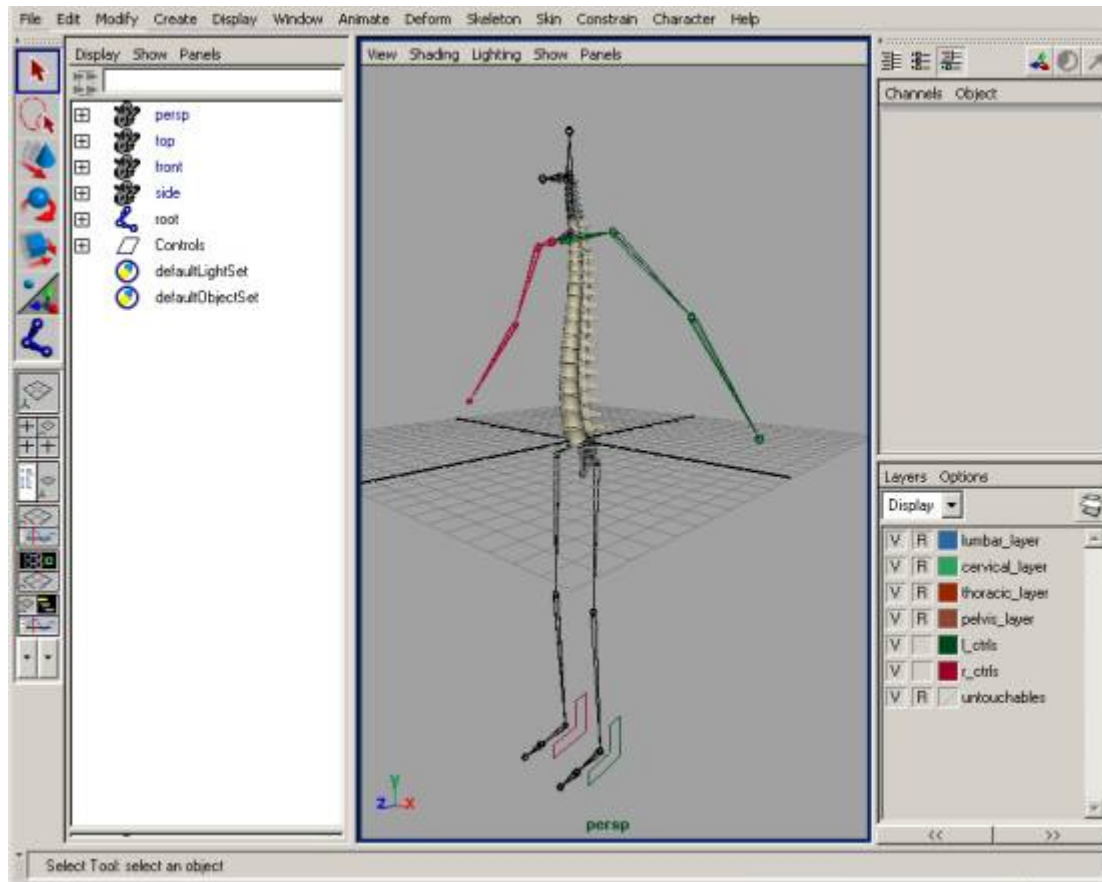
CREATING THE BACK

Notes on joints created for the back

- Use the joint tool to create a common s-curve back shape. The more joints you use, the better, as these joints are merely going to be a representation of the curve used to manipulate them.
- Orient the joints correctly using **jsOrientJoint**. This script will allow you to make sure the joints all are oriented towards eachother, and facing the correct direction. It's extremely important for the joints to **ONLY** have translations in Y, as this is the axis we're going to be scaling them in.

Generate splinelk for the back joints

backSolver_start.mb

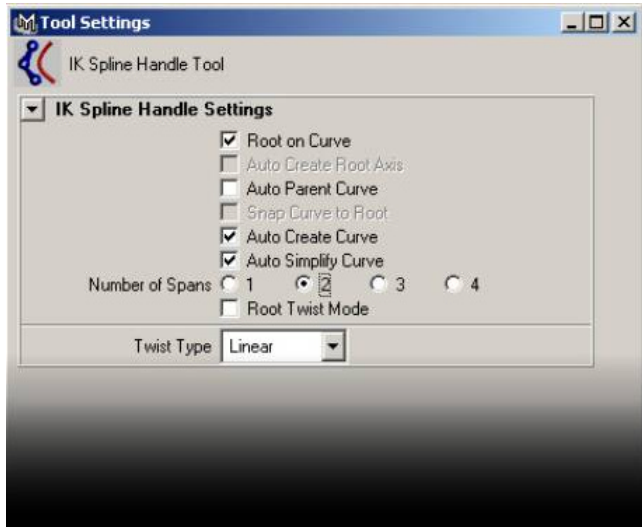


- Open the file **backSolver_start.mb** .

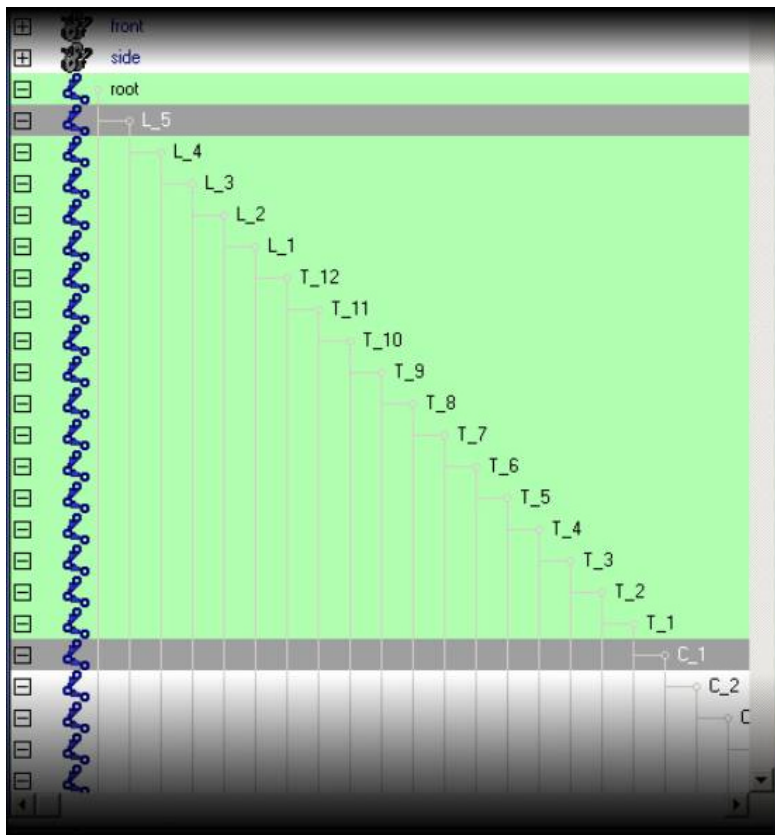
This file has a back already generated using the above method, with geometry parented underneath so you can see what the back is doing when it's rotated.

- Choose the IK Spline Handle tool and bring up the option box.

Auto create Curve to On,
Root on Curve to On
Auto Simplify Curve to On.
Auto parent curve to off.
Set Auto simplify curve to 2.



Choose **L_5** and **C_1**. This will create an ikHandle and a curve from the lumbar joint to the cervical. Name the curve "**back_curve**", and the ikHandle "**back_ikHandle**".



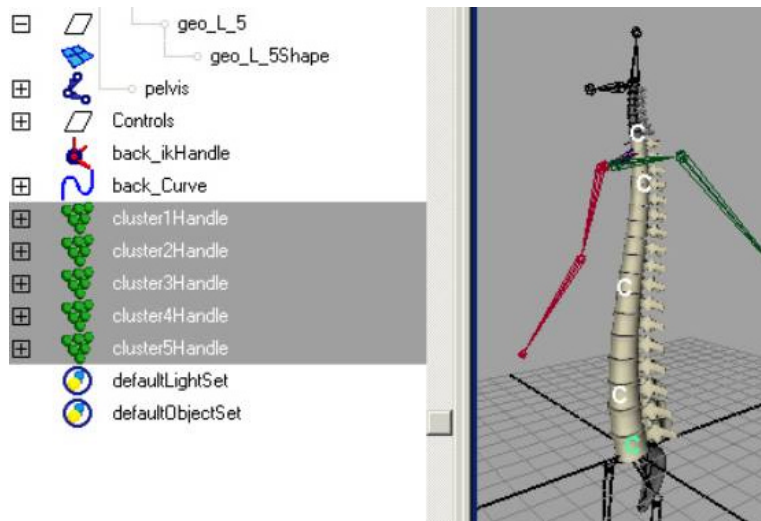
- Hide the ikHandle.

Create clusters for the curve.

In order to move the back around, we're going to create two main controls. A

shoulder control and a hip control. These controls will move the curve through the use of clusters.

- Create a cluster for each cv on the curve.



Create "stretchyness" on the joints.

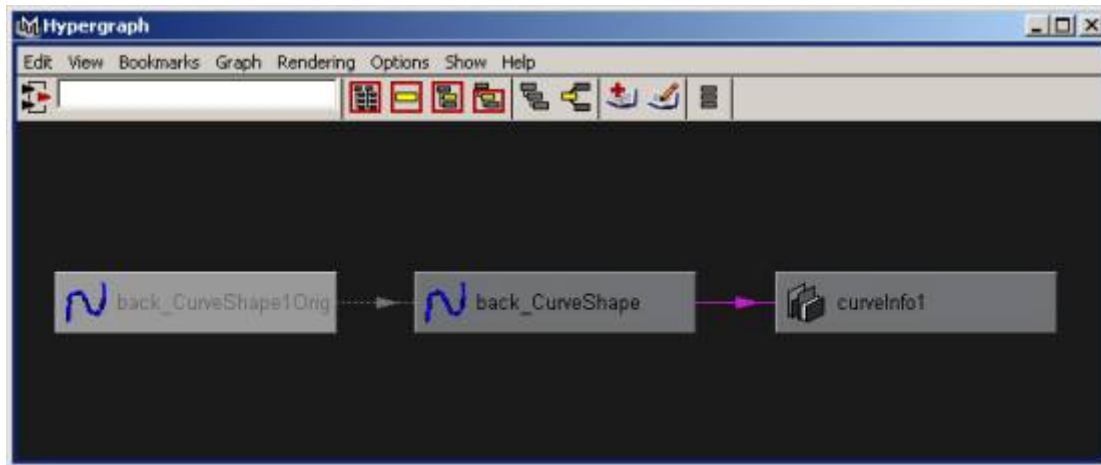
We need to allow the joints to stretch in order to make the control work correctly. To do this, we measure the arcLength of the curve. Divide the original arcLength by the current arcLength, and multiply that result by each of the joint's original **translateY** attributes. This value will be what the joint's new **translateY** will be.

- Select the curve and type:

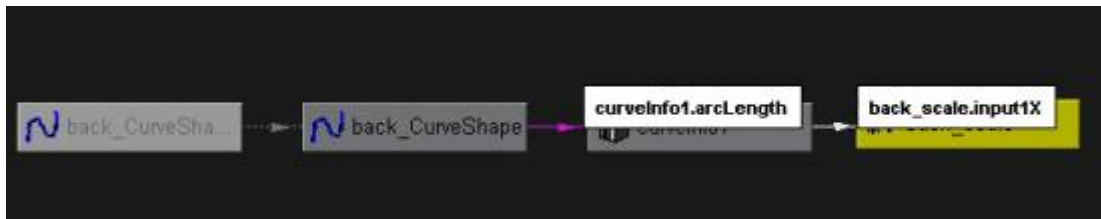
arclen -ch 1;

This adds a node called curveInfo1. This node contains the arclength of the curve (a approximation of the true length of the curve).

*Note: If you want to simplify the display of the hypergraph as shown below, you can use the **Show > Show Selected Type** option with nodes that are selected.*



- Create a **multiplyDivide** node which will measure the length of the curve and output a scale value (the scale of the curve relative to it's initial length).
- Name the multiplyDivide node "**back_scale**".
- Connect the arcLength value of the curveInfo node and put it in the **input1X** of the **multiplyDivide** node.

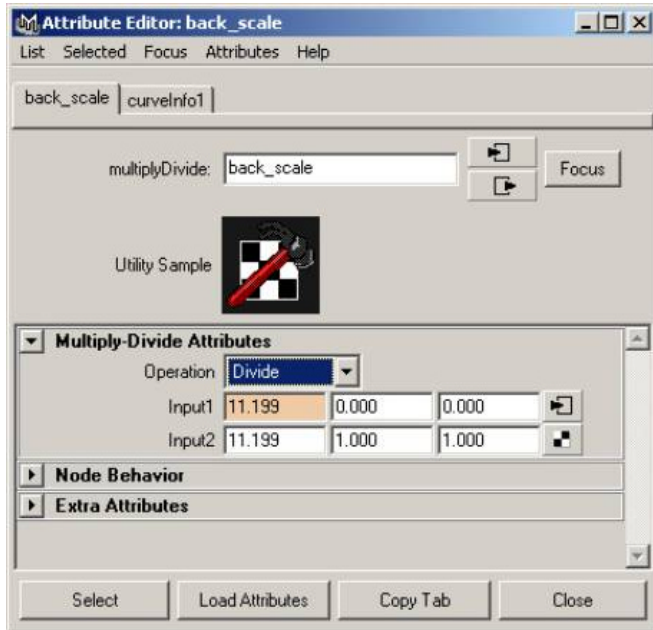


- Take the current arcLength value of the curveInfo node and put it in the **input2X** of the **multiplyDivide** node.



- Set the Operation attribute to "Divide".

This will give you the scale. When the two values are the same, the "scale value" will be 1. When the curve is half it's length, the scale will be .5. When it's twice it's length it will be 2. We're going to use this scale value to adjust the torso joint **translateY** attributes.



We start stretching from **L_4**, because you don't want to change the translateY on the first joint (it will cause the joint to go off the curve).

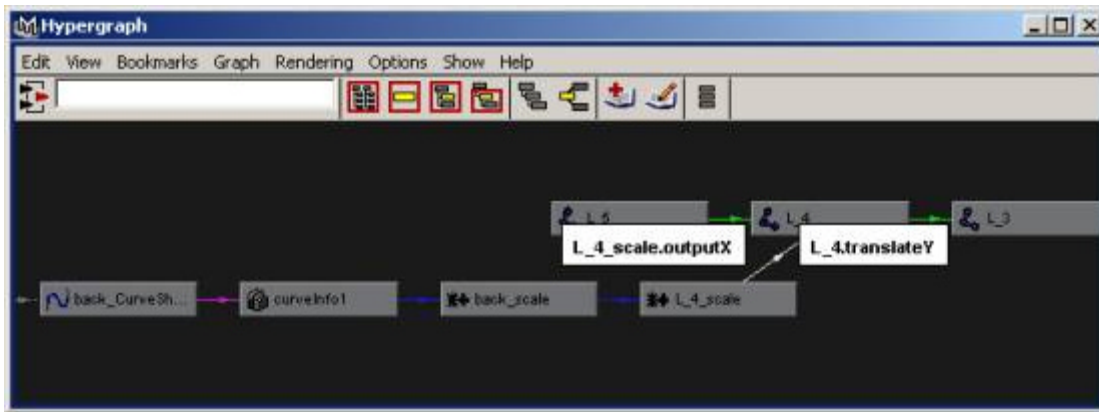
- Create another **multiplyDivide** node.

This one will be used on **L_4** (call it **L_4_scale**).

- Copy the **L_4.ty** value and put it in **L_4_scale.input2X**.
- Connect the **back_scale.outputX** attribute to **L_4_scale.input1X**.



- Connect **L_4_scale.outputX** to **L_4.ty**;

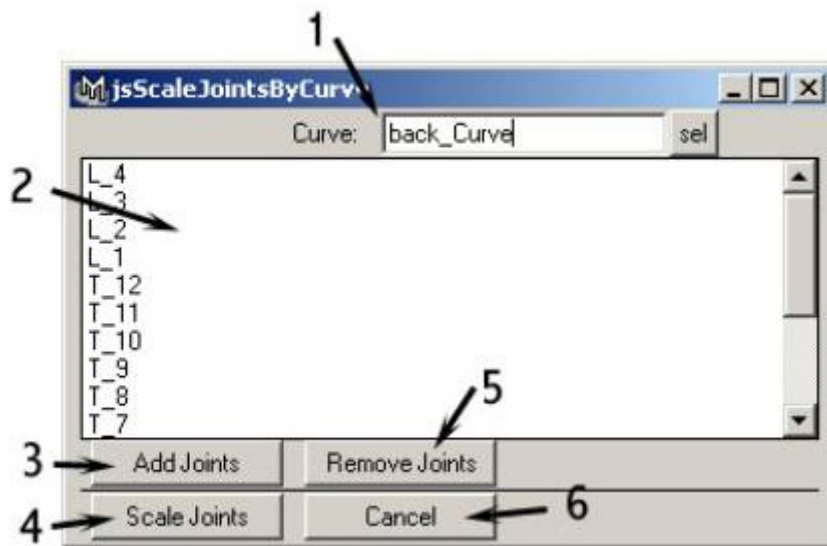


Now when you scale the curve, you should see L_4.ty changing.

Using jsScaleJointsByCurve to Automate Back Scaling

To make this process easier, you can use the jsScaleJointsByCurve script which will hook up the given chosen joints to the given curve.

- Bring up the **jsScaleJointsByCurve** interface by typing **jsScaleJointsByCurve** in the script editor.



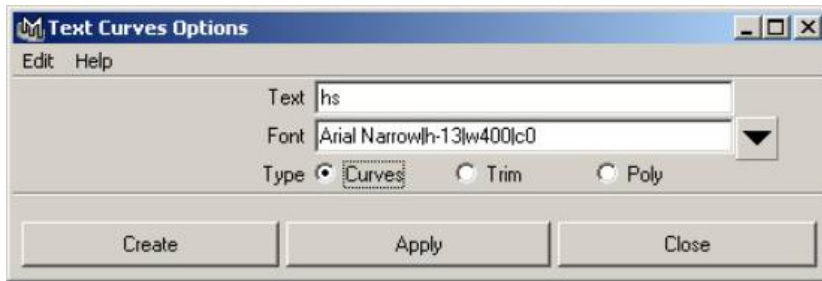
1. Curve to measure.
2. All the joints that are going to be scaled.
3. Add a joint to the list.
4. Apply the scale joint command.
5. Remove joints from the list of joints.
6. Close the interface.

- Select **back_curve** and click **sel** in the "curve" area of the **jsScaleJointsByCurve** interface.
- Select all the joints from **L_4** through **C_1**.
- Click **Add Joints** In the **jsScaleJointsByCurve** interface.
- Translate the clusters around to see the back scale.

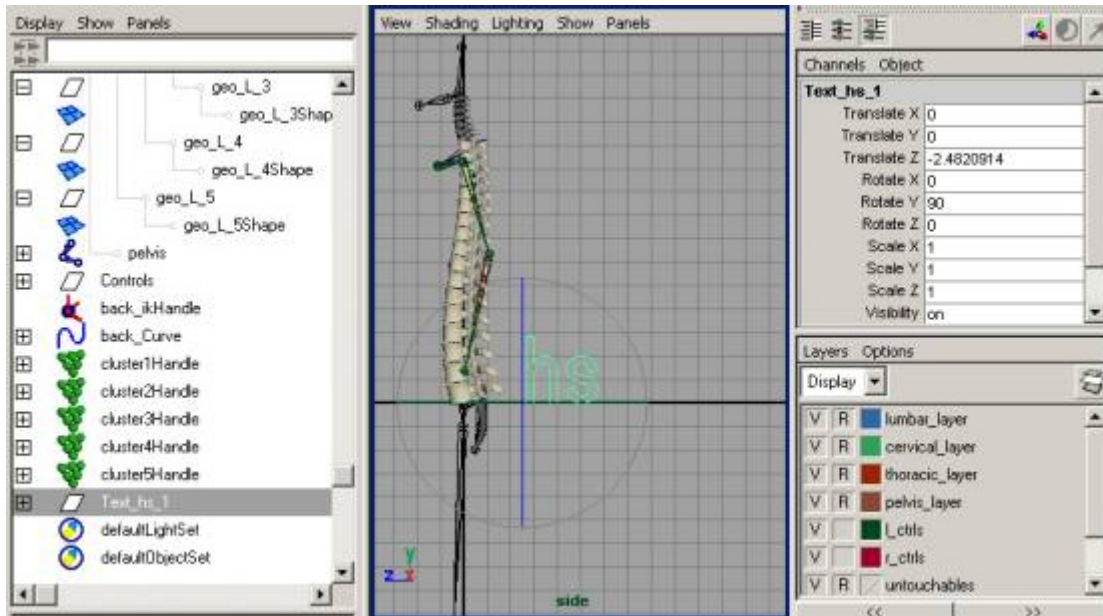
Create hip and shoulder controls.

To control the back, we're going to use a hip and shoulder control setup.

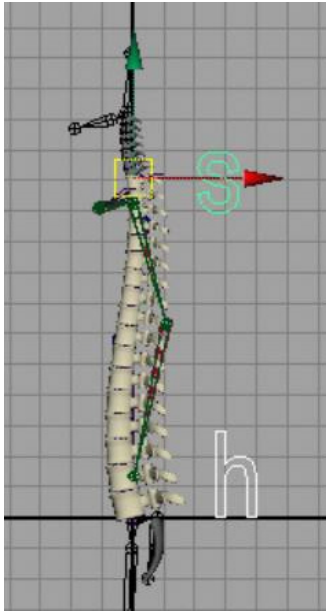
- Create two text curves, one "h" for hip and one "s" for shoulder.



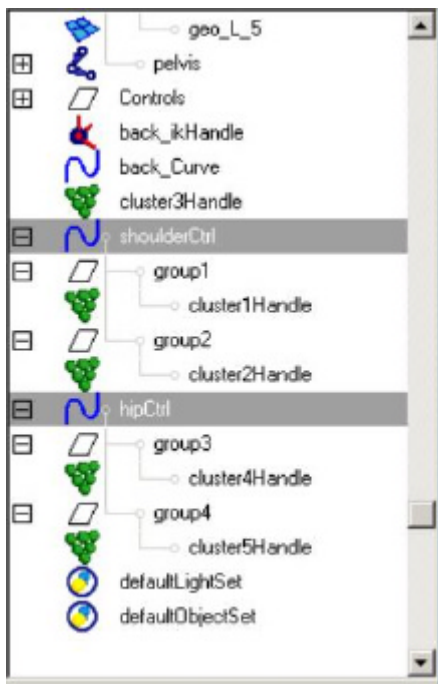
- Rotate the controls **90** deg in **Y** so they face the correct direction.



- Label the "s" "**shoulderCtrl**".
- Label the "h" "**hipCtrl**".
- Move the pivot for **shoulderCtrl** to **C_1**.
- Move the pivot for **hipCtrl** to **root**.

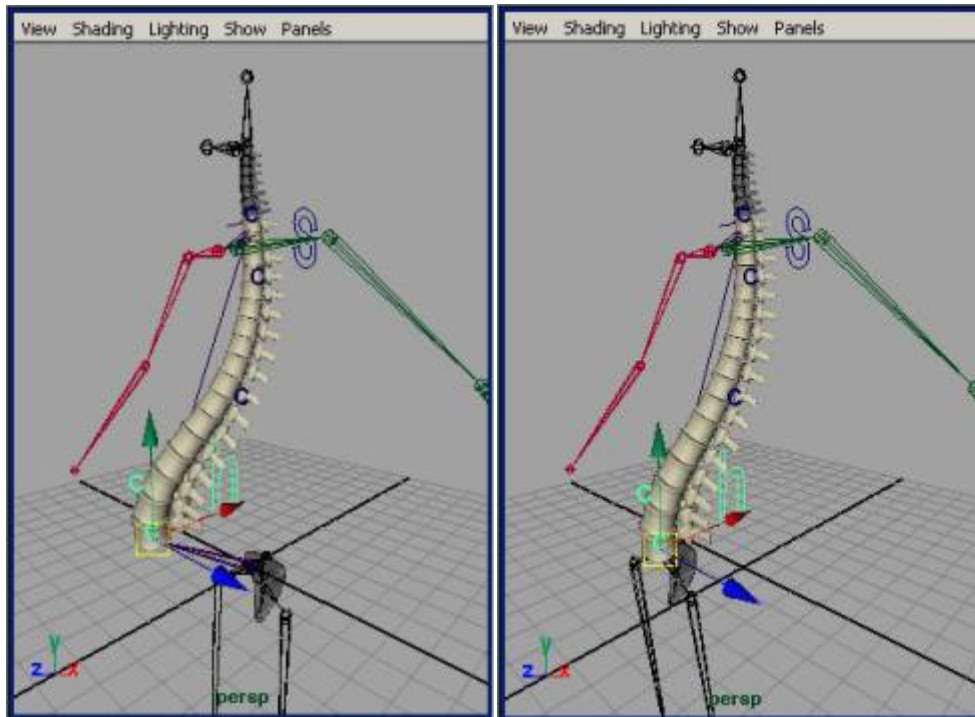


- Parent the top two clusters to the **shoulderCtrl**.
- Parent the bottom two clusters to the **hipCtrl**.



Move the hip control and notice how the root doesn't move with it.

- Use **jsConstObj** to constrain the root to the hip control. (Select **hipCtrl**, select **root**, type **jsConstObj**. Or, you can point and orientConstrain the root to the **hipCtrl**).



Now when you move the top two controls, you'll notice the back moves around, aside from the middle cluster. This middle cluster is a stabilizing control used mainly to make the FK part of the control more stable.

Create Stabilizing and FK controls

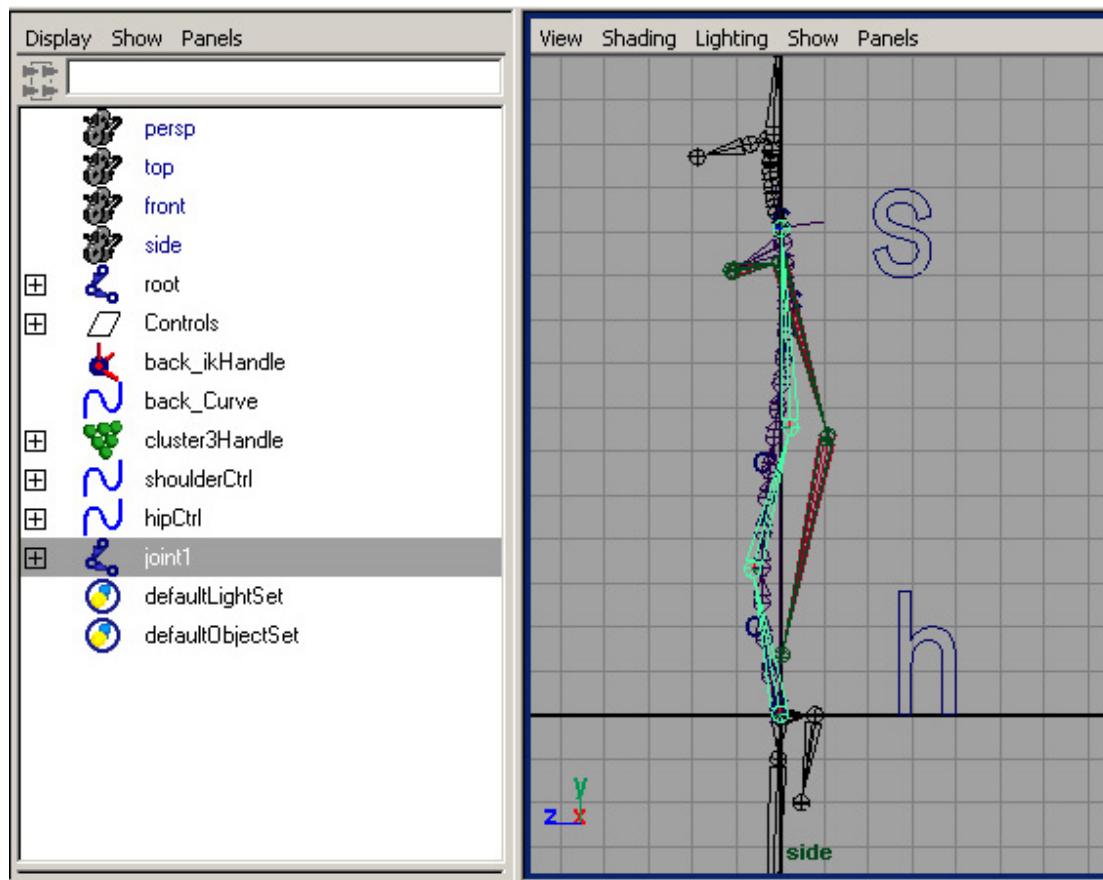
The stabilizing cluster is going to be constrained between the shoulder and hip controls.

- Select the **hipControl** and the **shoulderControl** and the middle cluster.
- Use **jsConstObj** to constrain it to both of them.

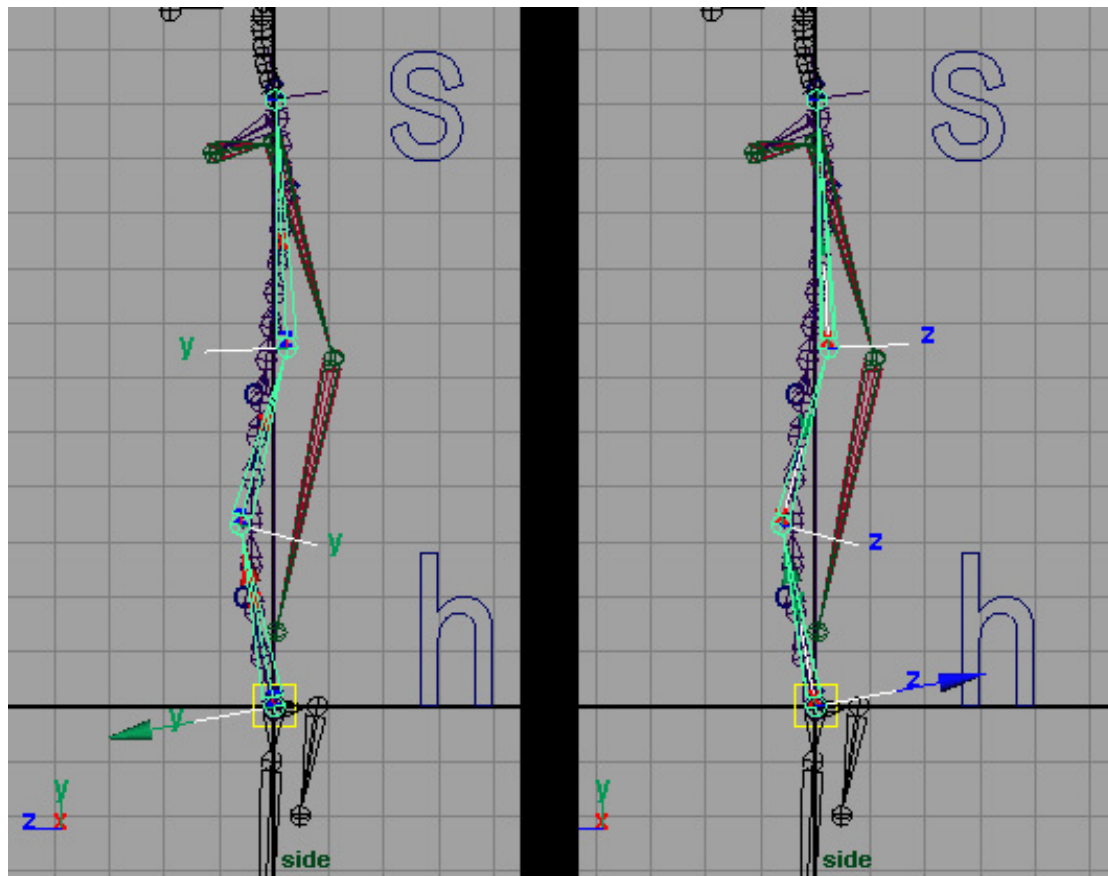
`jsConstObj` is a mel script which will automatically create a point and orient constraint for an object. It also ties the point and orient constraints together, and adds attributes to the object being constrained to allow for easier manipulation of the constraint weights.

Now create the joints which we're going to use to animate the back.

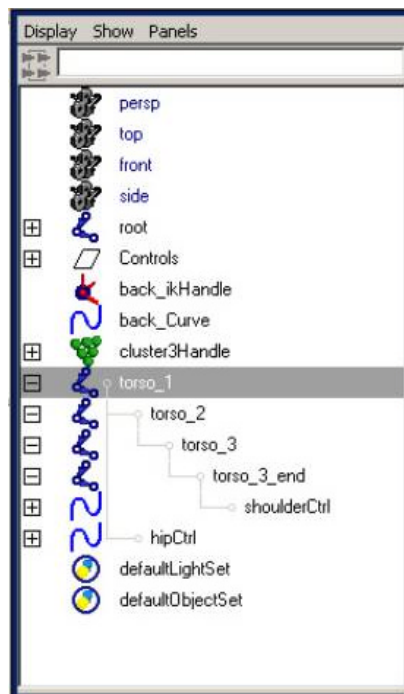
- Create three skeleton segments, one which starts at the root and goes 1/3 of the way up the back, then another which goes 2/3 up, and the last which ends at the neck (C_1).



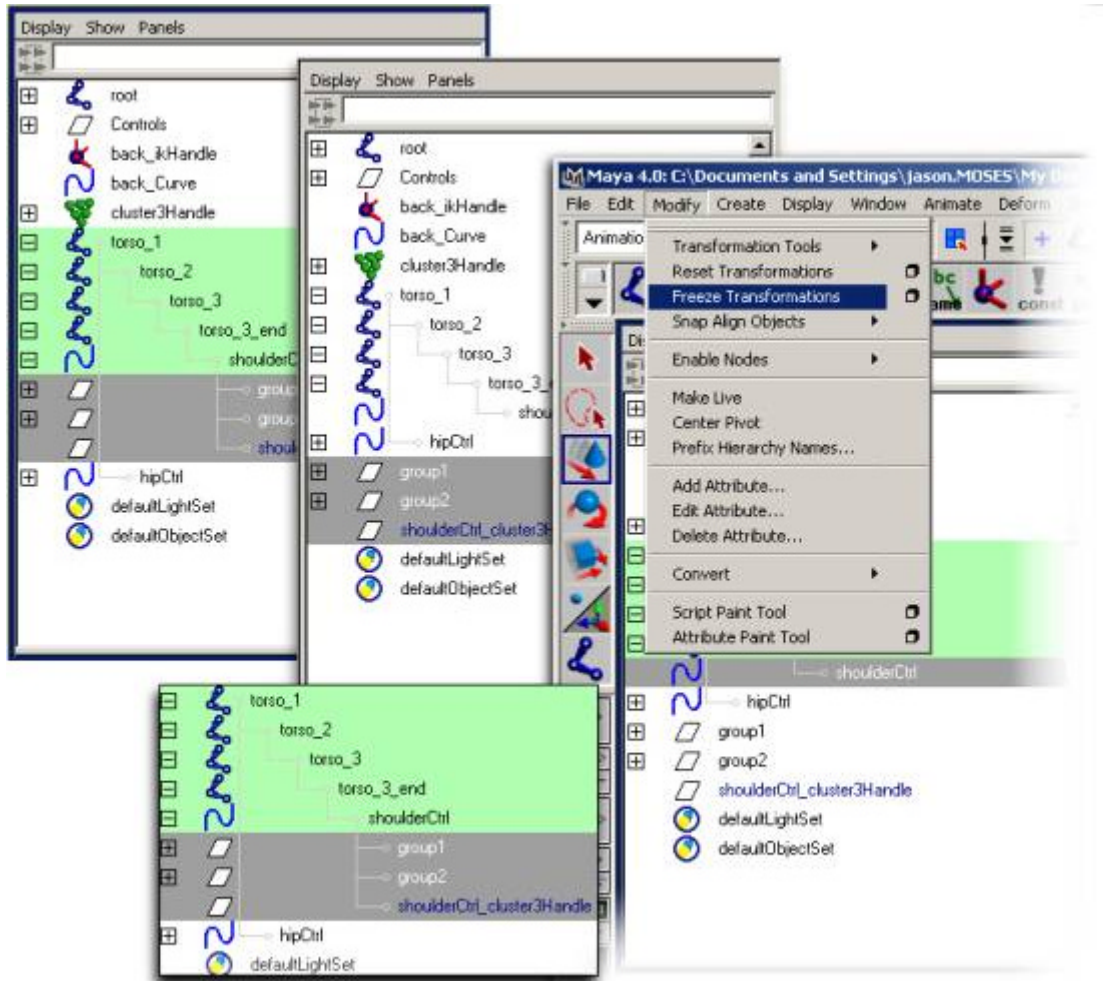
- Use **jsOrientJoint** to orient the joints correctly.



- Name the joints **torso_1**, **torso_2**, **torso_3**, and **torso_3_end**.
- Parent **shoulderCtrl** under **torso_3_end**.
- Parent **hipCtrl** under **torso_1**.



- Make sure **hipCtrl** and **shoulderCtrls** are **0 0 0**.
 - For **shoulderCtrls**, unparent the children, select **shoulderCtrl**, perform Freeze Transformations, and re-parent the children.



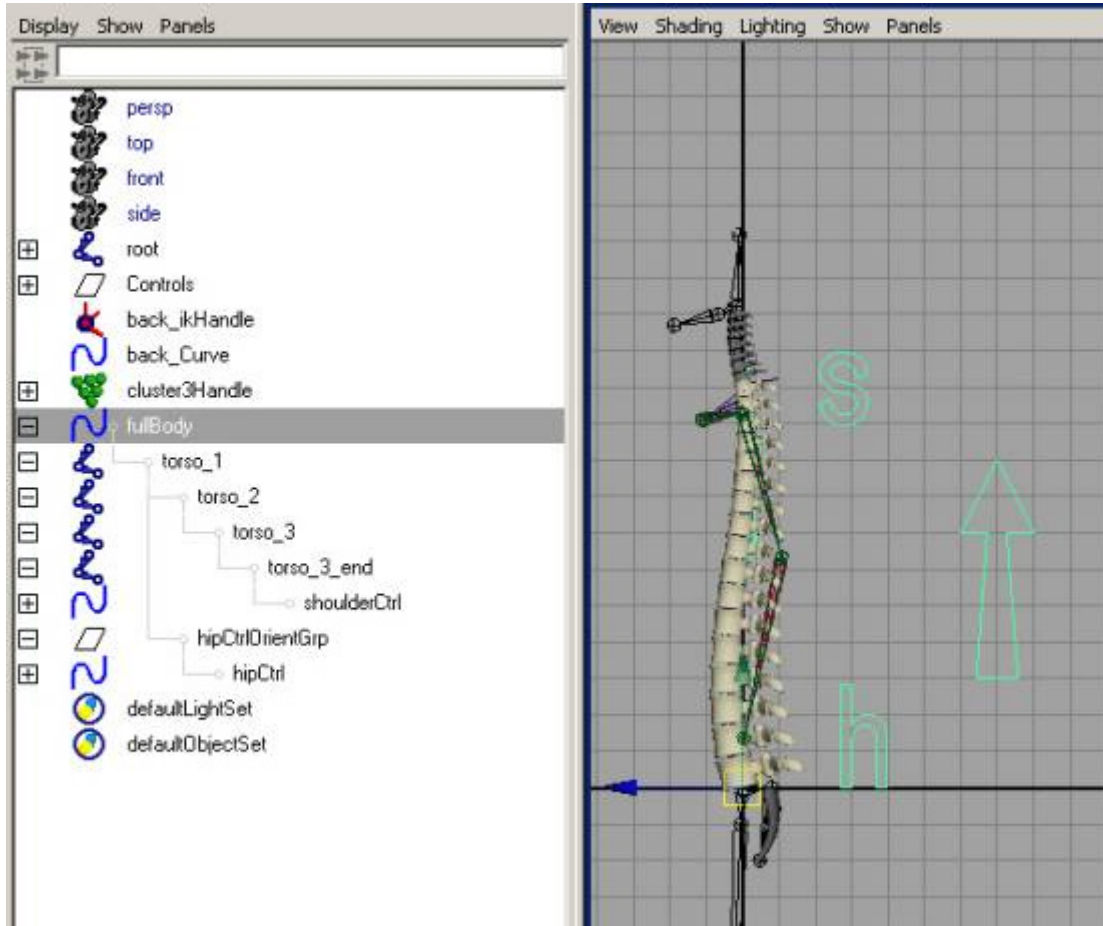
For **hipCtrls** we need to do something a little bit different. If you perform a freeze transformations the same as done for the shoulder controls, then the orientation of the hip control won't be aligned correctly with the world.

- To fix this, unparent the **hipCtrl** children as you did with the **shoulderCtrl** children.
- Group **hipCtrl** to itself to make a group above it, and rename that group **hipCtrlOrientGrp**.
- Measure the **jointOrientX** attribute of the **torso_1** joint and subtract that value from **180**.

This will give you the amount that you need to rotate **hipCtrlOrientGrp** to get the **hipCtrl** to align correctly. For example, use the following mel command:

setAttr hipCtrlOrientGrp.rx (180-`getAttr torso_1.jointOrientX`);

- Now freeze transformations on hipCtrl, and re-parent the children.
- Create a "fullBody" control that can be used to animate the entire back, fk, ik, and all. This can be a curve which is easily recognizable.
- Parent torso_1 to fullBody.

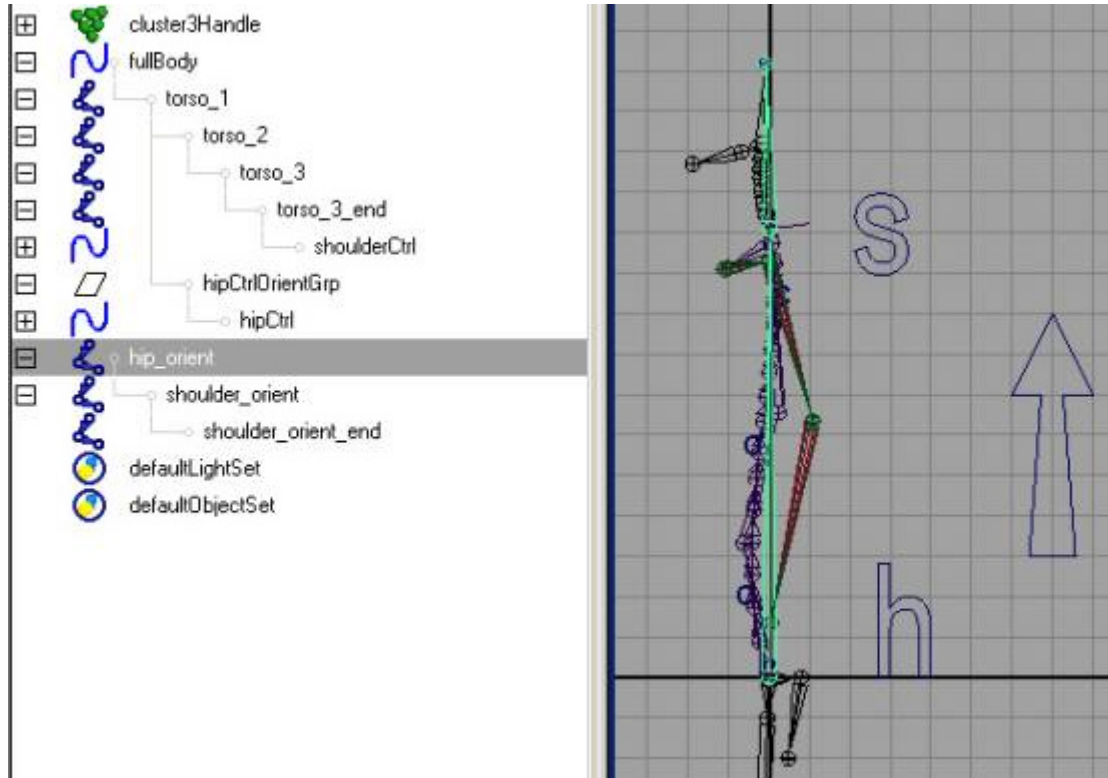


Add twist to the back

Currently the back will move around with the controls, but not when you try and twist it. This next step will create the control for twisting the back in any direction. Note: This technique will work with rotations up to 180 degrees. If the back rotates past it, it will flip. However, It's not physically possible to rotate your back past 180 degrees anyway, so this shouldn't be too much of an issue.

- Create a joint structure which goes from the root to the neck, and then from the neck to the top of the head.
- Name the joints "hip_orient", "shoulder_orient", and

"shoulder_orient_end".



- Use **jsOrientJoint** to orient the joints correctly. Set the rotation order on all of them to **xzy**.

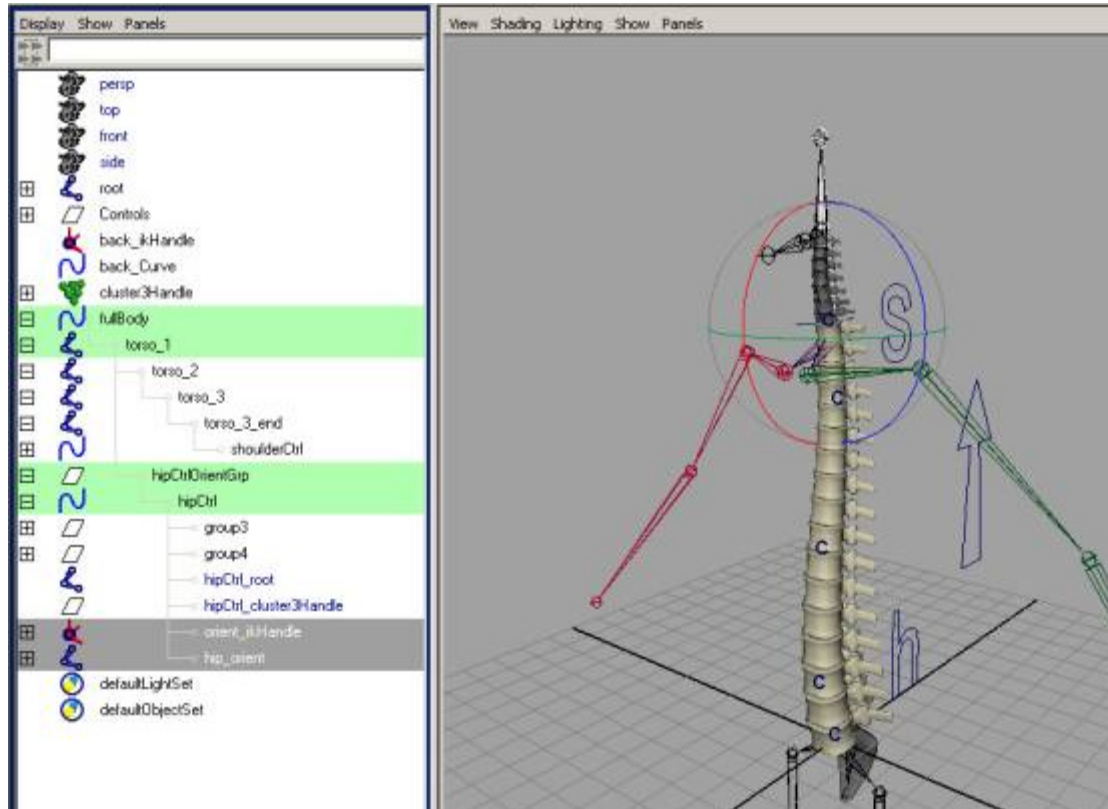
We're going to use the y rotation of "shoulder_orient" to drive the twist value of the ikHandle.

- Create a **ikSCsolver** ikHandle from "hip_orient" to "shoulder_orient", name it **orient_ikHandle**.
- OrientConstrain **shoulder_orient** to **shoulderCtrl** (use **jsMakeOrient** and delete the pointConstraint).
- Make an expression on back_ikHandle that connects **shoulder_orient.ry** to **back_ikHandle.twist**

(Note: you MUST do an expression for this. A direct connection breaks it).

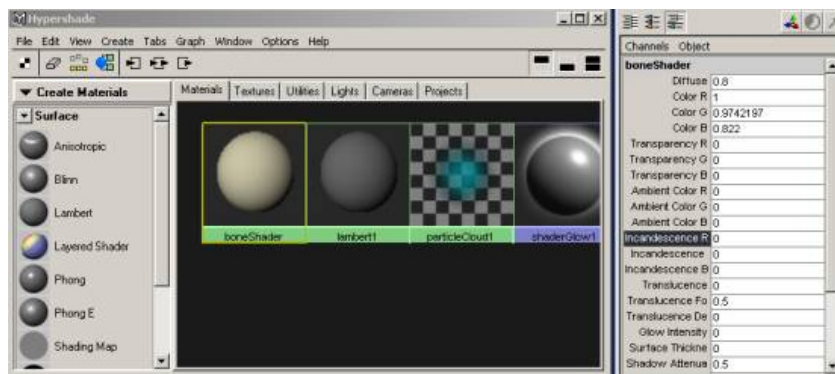
back_ikHandle.twist = shoulder_orient.ry;

- pointConstrain the **orient_ikHandle** to **shoulderCtrl**.
- parent the **orient_ikHandle** and **hip_orient** to **hipCtrl**.



Add Stretch Warning Color

While this has lots of control to move things around, it's good to warn the animator if they're taking things too far. You can do this using a "stretch" warning color.

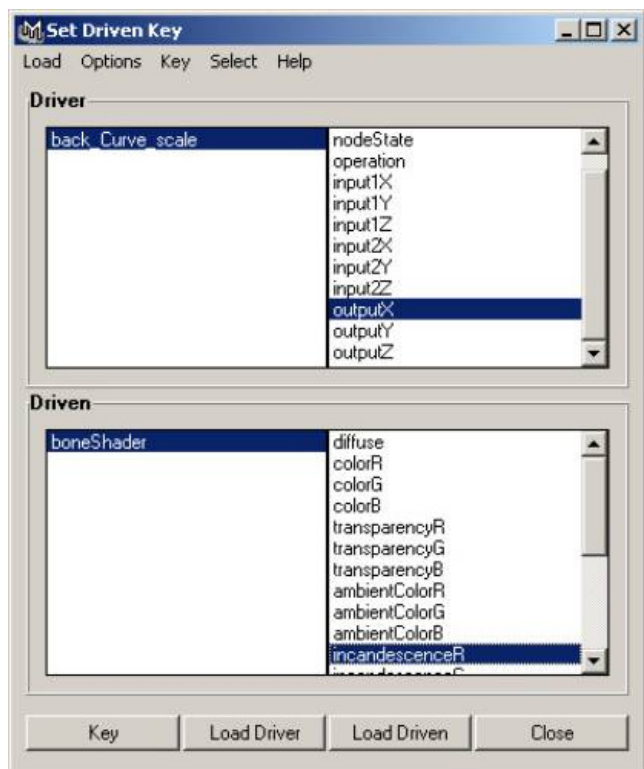


- Bring up the hypershade and select the **boneShader**.

We're going to use the **incandescenceR** channel to let the animator know if they're stretching things too far.

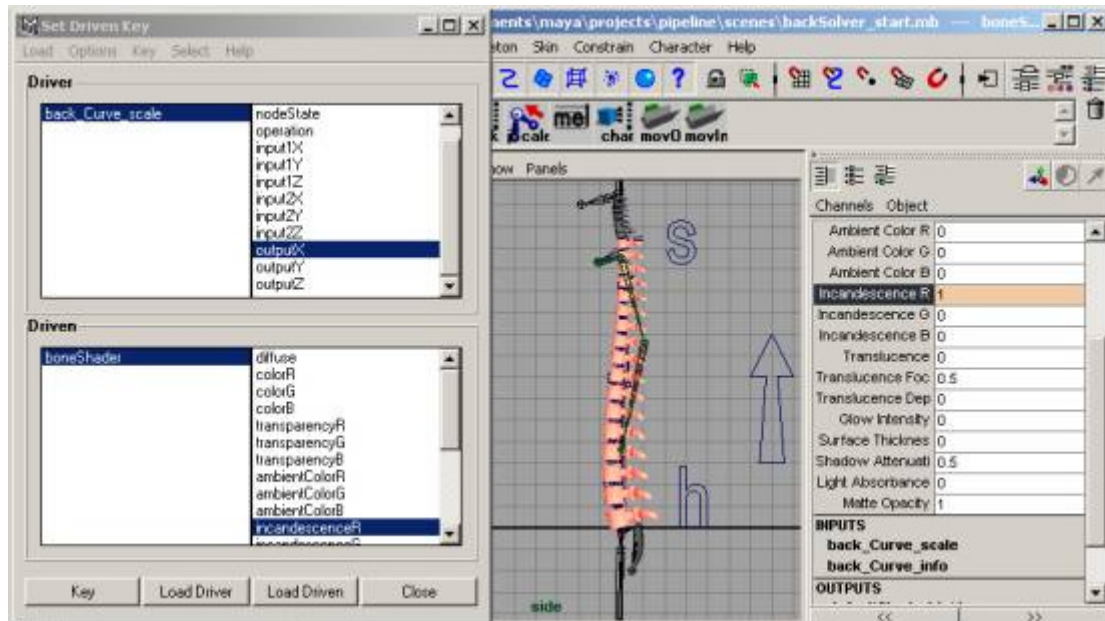
- Select the **incandescenceR** channel in the channel box and click the **RMB** to bring up the setDrivenKey dialogue.

- Select the **backCurve** and bring up the hypergraph.
- Graph the dependency graph for the curveShape. Pick the back_curve_scale and put it in the drivers column of the setDrivenKey window.

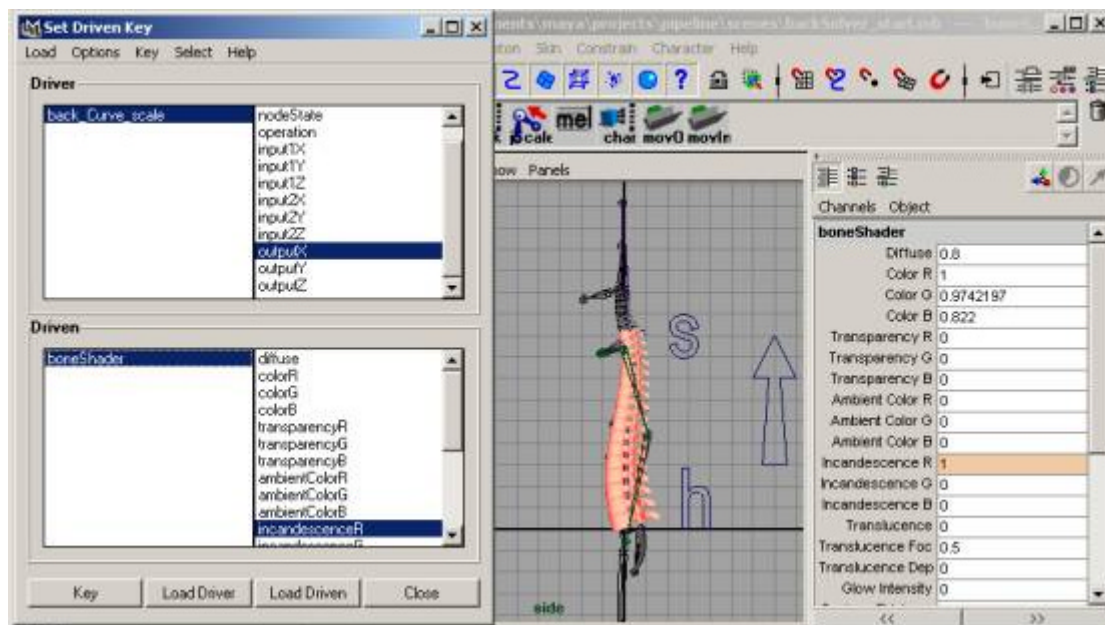


outputX is the item which is driving the scale. We'll use it to drive the incandescenceR of the shader.

- Select those channels, and hit **Key**.
- Move **shoulderCtrl** up a bit until the back is stretched as far as you want to allow it.
- Select the shader in the setDrivenKey window and in the channel box change **incandescenceR** to 1.



- Press **Key**.
- Move the control down so the back is compressed as much as you want it to be.
- Change the **incandescenceR** to 1



- Press **Key**.
- Now alter the curves in the graph editor to give you just as much stretching as you want to allow.

Clean everything up for the animator

- Assign all joints and controls which you don't want the animator to have

access to a display layer called "untouchables". These will be in reference mode.

- Assign the torso controls to a displayLayer called "**torsoCtrls**". Color it in a way that would make it easy to see.
- Assign the back cuve controls to a displayLayer called **backCtrls**;
- Turn on display handles for the joint-based torso controls.
- Check all rotation orders so they behave how you'd expect. (e.g. the ik controls should be **xzy** so the body can rotate around in any direction).

VIII. Procedural Animation Rig

What is a "procedural animation rig"?

The idea behind the procedural animation rig is to provide automated and consistent ways of creating and updating rigs. If the directory structure for generating rigs is consistent, and you have mel scripts written to build controls for the character, it's possible to make scripts which will build an animation rig from the ground up in a matter of seconds.

Creating a procedural animation rig

Here are the basic steps one could take in building a rig for their character:

- Import the skeleton
- Import the geometry and parent it to the appropriate joints.
- Define the "creature"
- Add arm controls
- Add leg controls
- Add back control
- Add head control
- Save File.

These steps can easily be broken down into mel scripts and commands if the locations for the files and the naming scheme for geometry and controls is consistent.

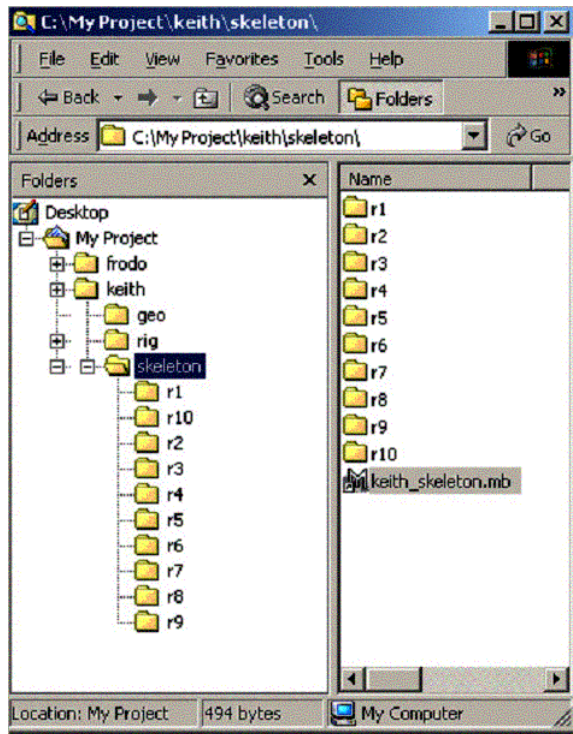
For example, if you have previously defined in your environment the location of all skeleton files as a global string **\$gSkelLoc**, all geometry files as **\$gGeoLoc**, and the location to save the rigs as **\$gRigLoc**, all you need to do is determine which creature you're building the rig for and the script can easily import the skeleton and geometry, combine them, and then save the file.

```
// get the creature
string $creature = "keith";

// define the global variables
global string $gBaseProject;
global string $gSkelLoc;
global string $gGeoLoc;
global string $gRigLoc;

$gBaseProject = "C:/myProject/";
$gSkelLoc = ($gBaseProject + $creature + "/skeleton/");
$gGeoLoc = ($gBaseProject + $creature + "/geo/");
$gRigLoc = ($gBaseProject + $creature + "/rig/");
```

Once you've defined where the files will sit, it's up to you how you locate them. The easiest thing to do is to have the file always named the same, and linked to the latest revision. For example, if you have 10 versions of the skeleton, you should have 10 directories in the skeleton directory called "r#", and one file in the directory called creature_skeleton.mb which is linked to the most recent version. That way it's easy to find the most recent version, for humans and for the script.



If the pipeline is set up correctly, you can just assume that the files are going to be named as you're expecting and not need to perform a search for it. But it's always good to check. To do that you can use the fileTest command:

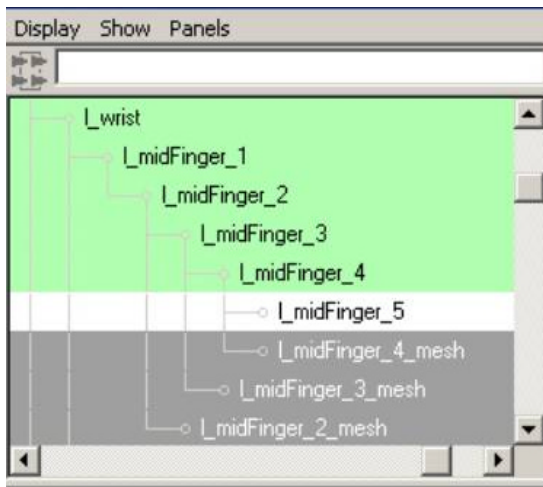
```
// IMPORT THE SKELETON
$skeleton = ($creature + "_skeleton.mb");

// check and see if the file exists and is readable
If (!fileTest -r ($gSkelLoc + $skeleton))
{
    // it doesn't exist! Error out.
    error ($skeleton + " in " + $gSkelLoc + " is not readable.\n");
}
else
{
    // it does exist.. import it.
```

```
file -import ($gSkelLoc + $skeleton);
```

```
}
```

Next we import the geometry using the same technique as above. Again, if the geometry is created of individual pieces which have the same names as the joints it makes it extremely easy to place them correctly on the skeleton. In the case below, all the geometry is named "joint_mesh". So the geometry for the root joint would be "root_mesh", and the geometry for the fingers would be "finger_mesh".



Then if your geometry is named correctly you can run a script like the following to parent it under the joints:

```
// PARENT THE GEOMETRY UNDER THE SKELETON
```

```
// find all the geometry
```

```
string $geos[0];
```

```
string $geo;
```

```
$geos = `ls -type transform ("*_mesh")`;
```

```
// for each bit of geometry, find the appropriate joint name and parent it.
```

```
for ($geo in $geos)
```

```
{
```

```
    // use the substitute command to find the correct joint.
```

```
    string $jointName;
```

```
    $jointName = `substitute "_mesh" $geo ""`;
```

```
    // check and make sure the joint exists
```

```
    if (!`objExists $jointName`)
```

```
    {
```

```
        warning ($jointName + " doesn't exist.. skipping..\n");
```

```
}  
else  
{  
  
    // parent the geo under the joint  
    parent $geo $jointName;  
  
}  
  
}
```

Now that all the geometry is parented correctly, you can define the creature using the methods shown in the previous lesson. The steps are as follows:

- Create a locator
- Add a "Creature" attribute to the locator.
- Add a multi attribute to connect the joints you want.
- Connect the joints/controls necessary to the attribute.

Once the creature is defined you have a good low-resolution version of your creature. It can be used for lighting, quick playblasts, rotoscoping, etc. It doesn't have all the nifty controls your final animation rig will have, but it does have the joints which will be driving the skinned version, so it can take animation just as the muscle model can take animation. It's a good idea to save this version of the file as a low-resolution lighting rig.

Now we start to add the controls. You can easily use mel commands to perform this, and if you have a consistent setup for how your creatures are generated, they can all take the same scripts. For example, if you have twenty bipedal characters in your scene, you only have to write the script for generating arm controls once, then you can apply it to each of your creatures.

After the controls are added, simply save the file as the most recent version (make a new revision number, and save the file in that directory, then make a link to it in the \$gRigLoc directory).

Updating an animation rig

Creating the rig is only first step in having a procedural system. While it's nice to be able to generate rigs by executing only a few commands, it's in updating the rigs that using mel becomes extremely handy.

If you have 12 animators all working on similar characters, and you need to make an update as to how some of the creatures are working, instead of going to each animator's computer and manually updating the scenes, it's much more time-effective to write a mel script to do it.

The trick to doing this is that joints and structures may not be named the same

as they were when you created the character (due to multiple creatures in the scene). So a script which would work with one character in the scene:

```
ikHandle -sj l_up_arm -ee -l_wrist;
```

suddenly doesn't work anymore because now there are two creatures in the scene, and maya doesn't know which l_up_arm you're talking about.

The fix for this is to know what creature it is you're wanting to update.

You can use the **ls** command with wildcards to find out all the instances of **l_up_arm**:

```
string $l_up_arms[0];  
$l_up_arms = `ls -long "*l_up_arm"`;
```

This will return the entire path of all the "l_up_arm"s in the scene.

Next we get a full path for the creature that we want in the scene. We can use the **findCreature** script created earlier to do this.

```
string $creatureFullPath = `findCreature "keith"`;
```

This will return the full path for the "keith" creature.

Note: If your production is going to have multiple creatures of the same type in the scene, you can modify the script to perform whatever update your making to each creature.

Once we have the full path for that creature, we can determine the top node in the hierarchy. For example, if the keith creature's full path is:

```
"|topNode|runAround|keith"
```

we want to grab "topNode" from this. You can do that using the tokenize command:

```
string $breakItUp[0];  
tokenize ($creatureFullPath, "|", $breakItUp);  
string $topNode = $breakItUp[0];
```

Note: The best thing to do here would be to define the above commands as a procedure called "findTopNode" which takes a string and returns the top node.

Now that we have the top node saved as \$topNode, we can iterate through the \$l_up_arms and find the one which has the same top node.

```
string $node;
string $l_up_arm; // this will be what we save l_up_arm as
for ($node in $l_up_arms)
{

    string $breakItUp[0];
    tokenize ($node, "|", $breakItUp);

    // check and see if $breakItUp[0] is the same as $topNode
    if ($breakItUp[0] == $topNode)
    {

        // we have a match! Put $l_up_arm as $node
        $l_up_arm = $node;

    }

}
```

Now we've found the correct \$l_up_arm that we were looking for.

If you wrap all those commands into a single script called something like "**findSpecificNode**" and took two arguments, the name of the node you're looking for and the creature you looking for it under, you could then write something which would look like this:

```
$l_up_arm = `findSpecificNode "l_up_arm" "keith";
$l_wrist = `findSpecificNode "l_wrist" "keith";

ikHandle -sj $l_up_arm -ee $l_wrist;
```

While this may seem like a pretty simple example, you can extrapolate this idea in to replacing anything on a creature. Not only replacing or adding controls, but modifying the current controls, copying animation from one control to another, even performing a "creature check" to make sure the animators haven't accidentally deleted anything.

By making sure you've build your rig in a consistant and procedural manner, you're providing yourself with a flexible method of generating and updating your creatures.